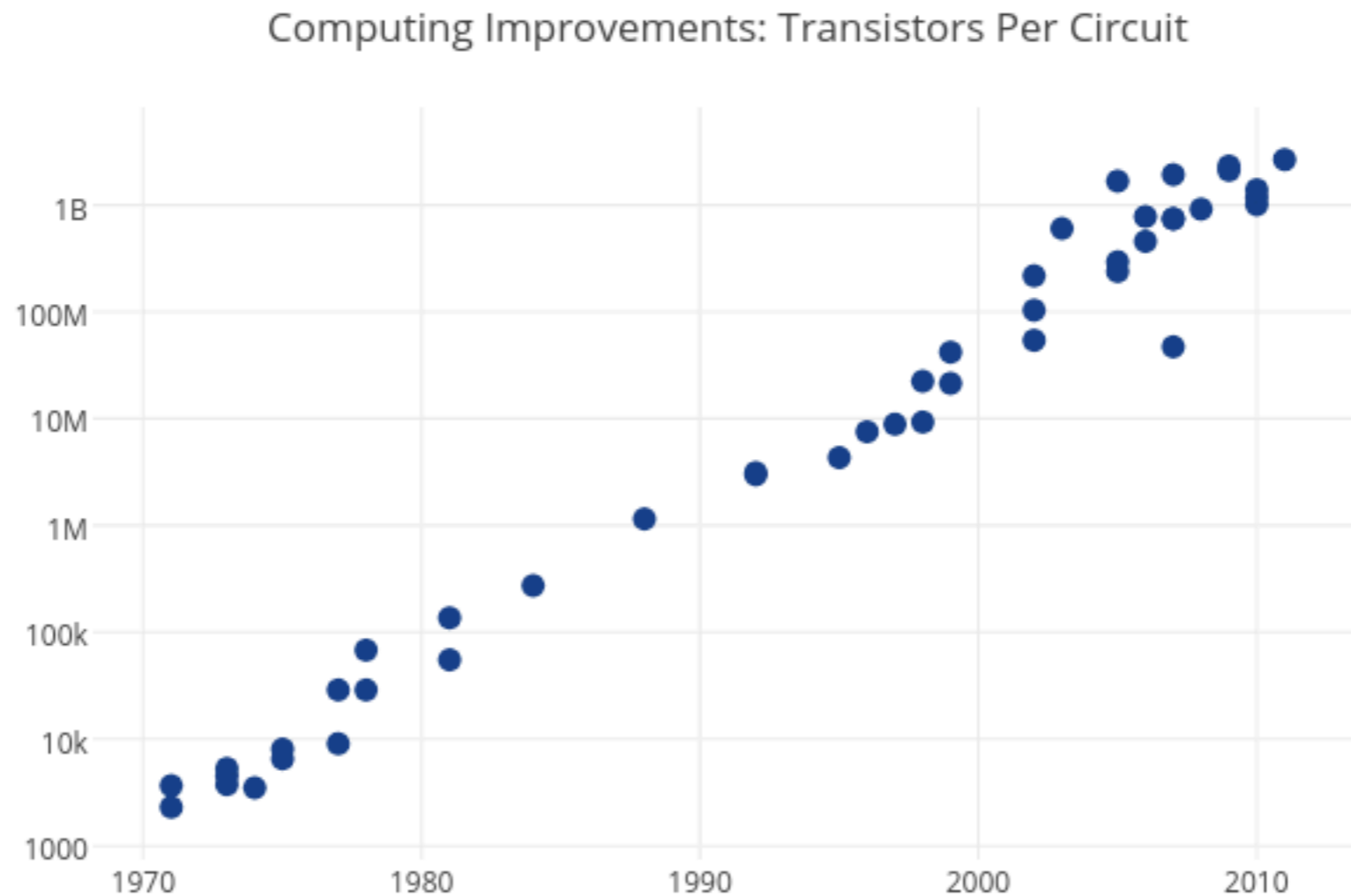


**95-865 Australia Lecture 2:  
Finding Possibly Related Entities,  
Visualizing High-Dimensional  
Vectors, Dimensionality Reduction**

George Chen

# Continuous Measurements

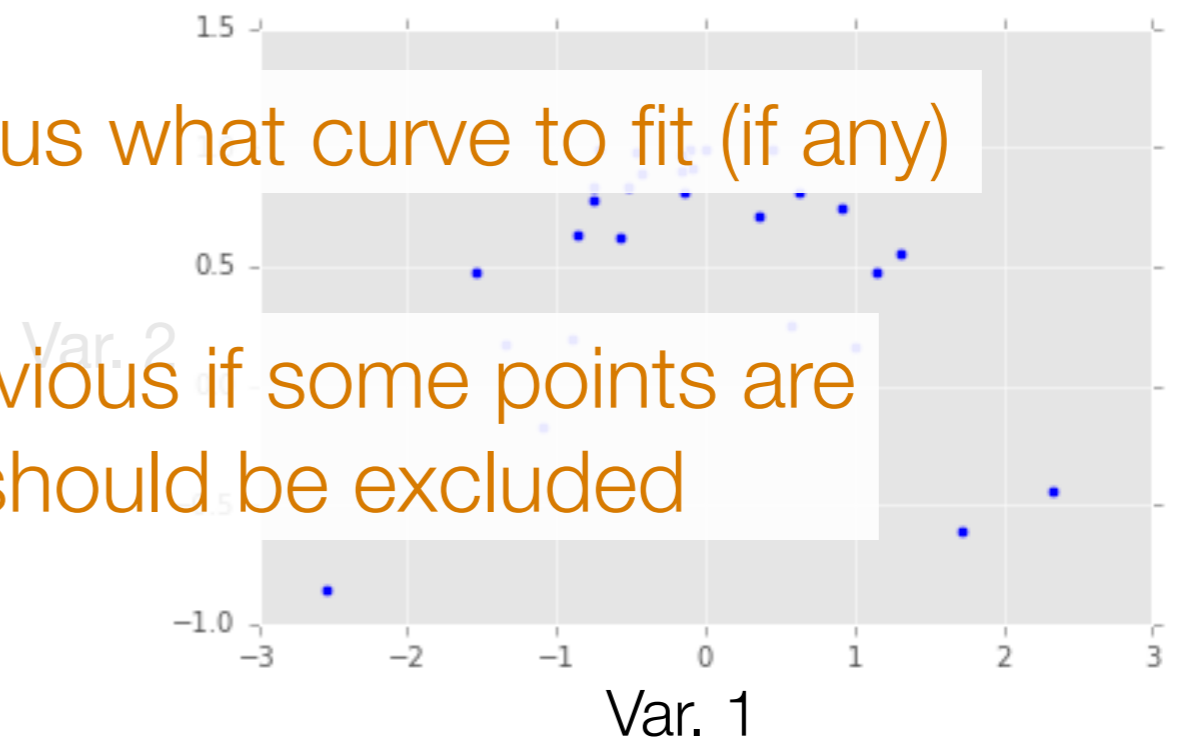
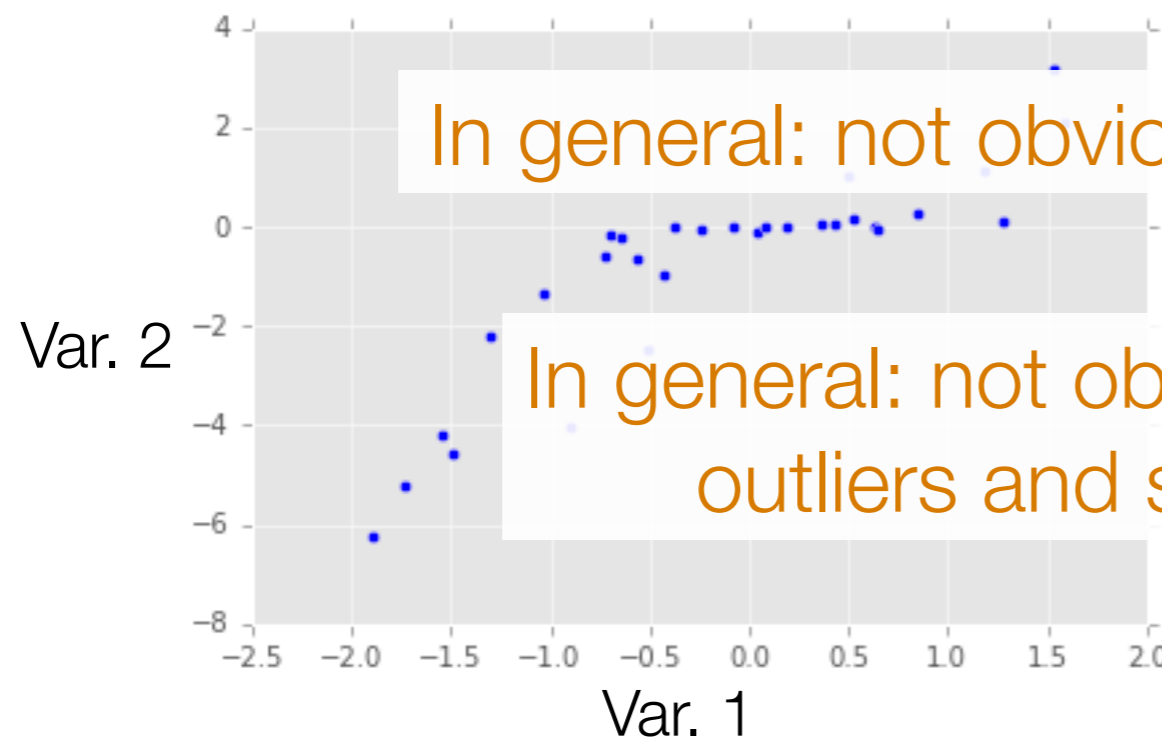
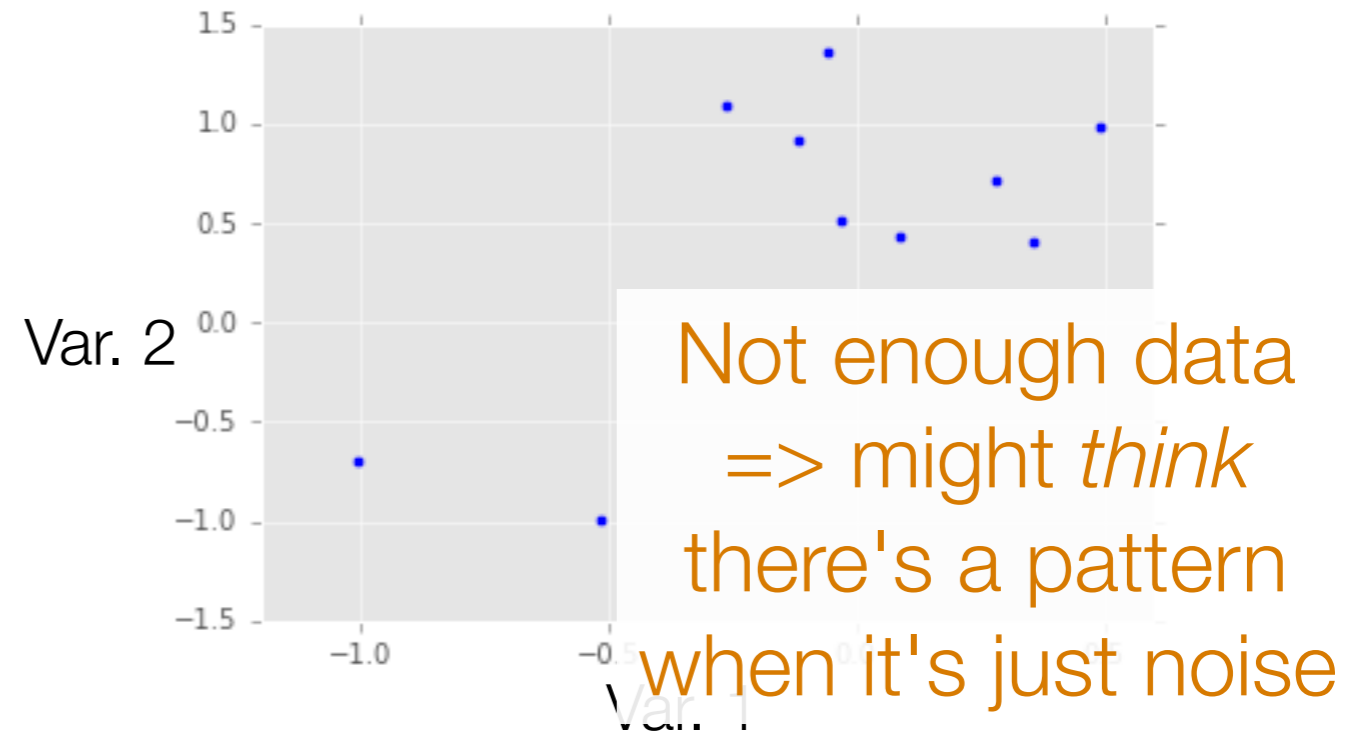
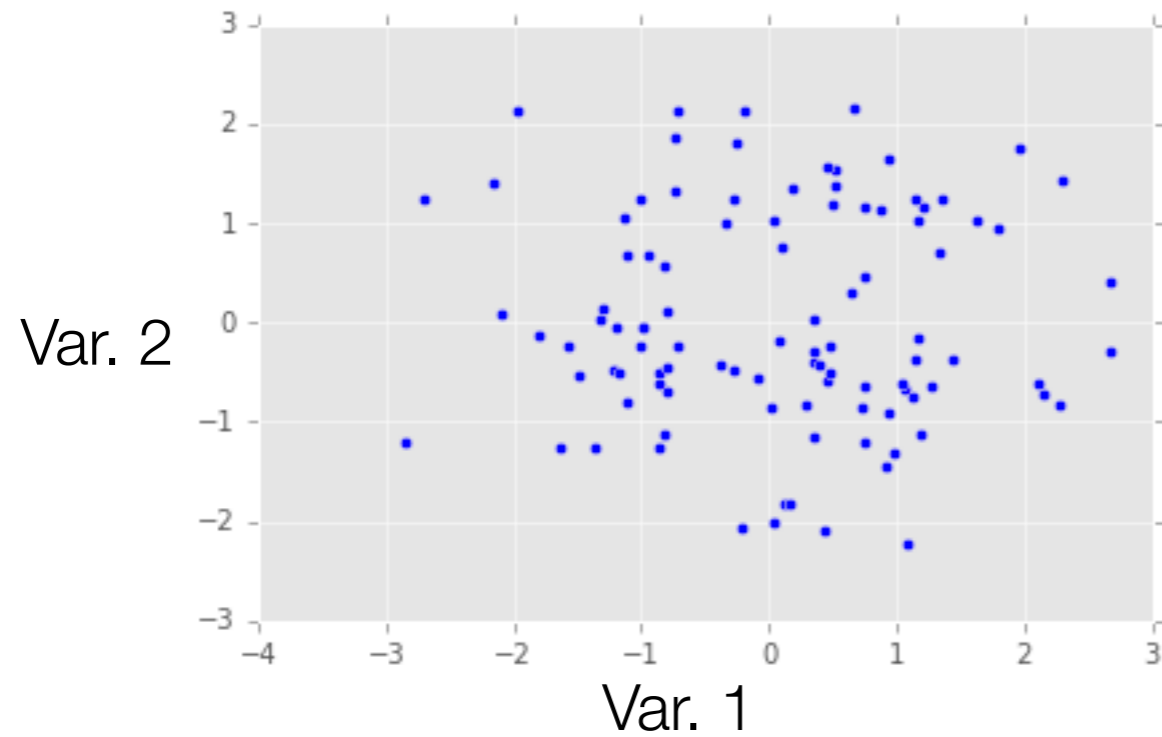
- So far, looked at relationships between *discrete* outcomes
- For pair of *continuous* outcomes, use a **scatter plot**



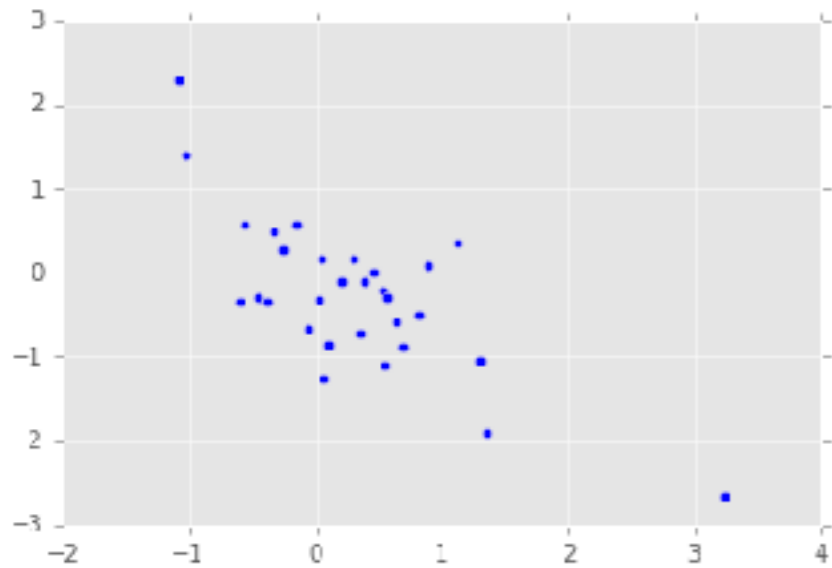
Of course, not all trends look like a line

(so don't just do linear regression!)

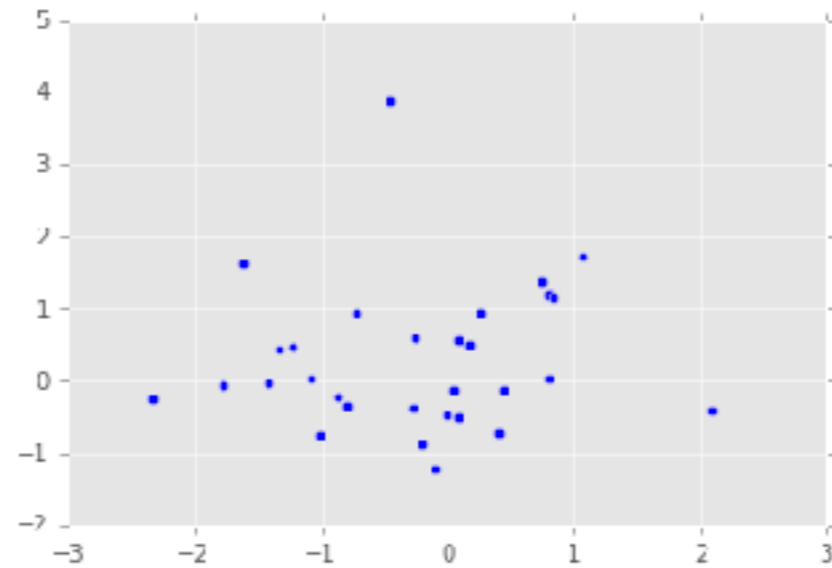
# The Importance of Staring at Data



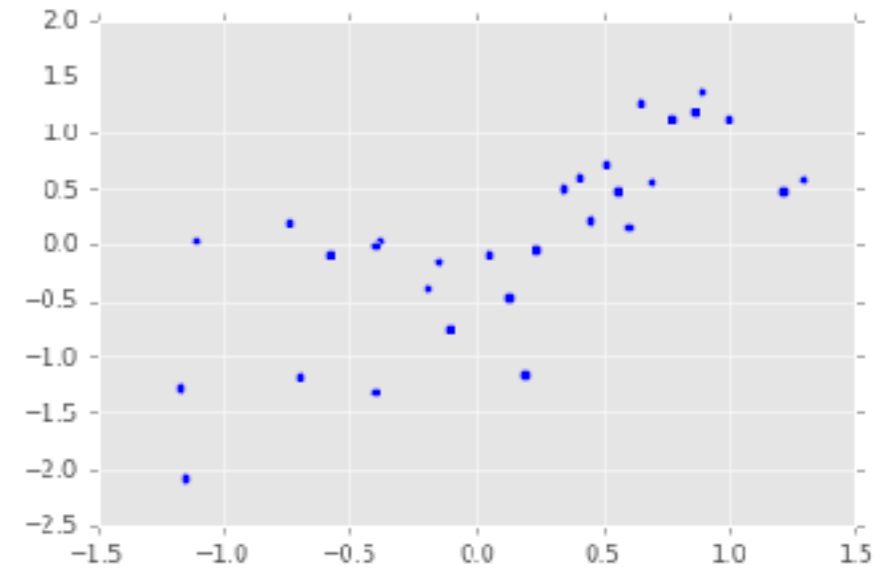
# Correlation



Negatively correlated



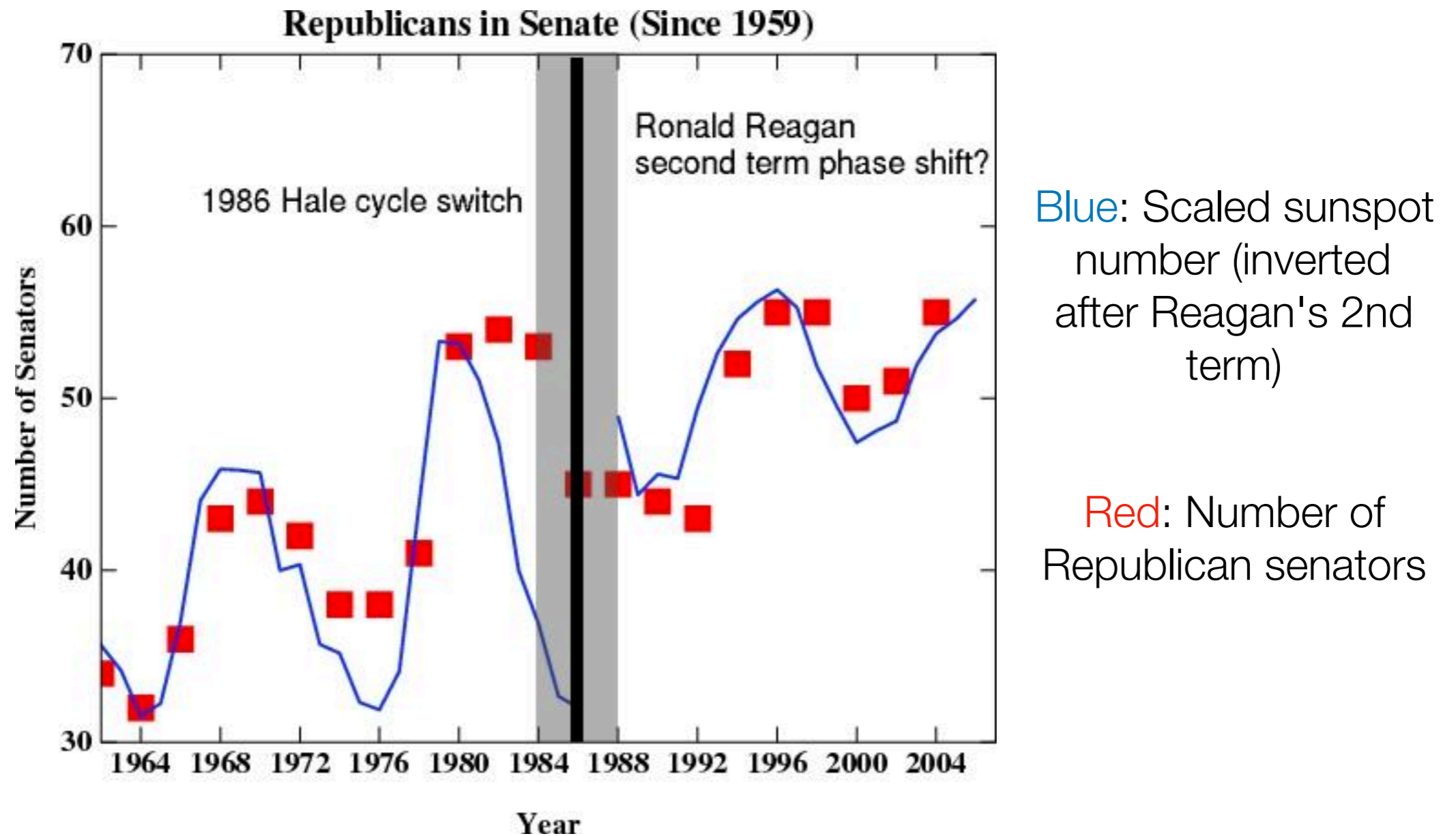
Not really correlated



Positively correlated

Beware: Just because two variables appear correlated doesn't mean that one can predict the other

# Correlation $\neq$ Causation



Moreover, just because we find correlation in data doesn't mean it has predictive value!

**Important: At this point in the course, we are finding *possible* relationships between two entities**

We are *not* yet making statements about prediction (we'll see prediction later in the course)

We are *not* making statements about causality (beyond the scope of this course)

# Causality



Studies in 1960's: Coffee drinkers have higher rates of lung cancer

*Can we claim that coffee is a cause of lung cancer?*

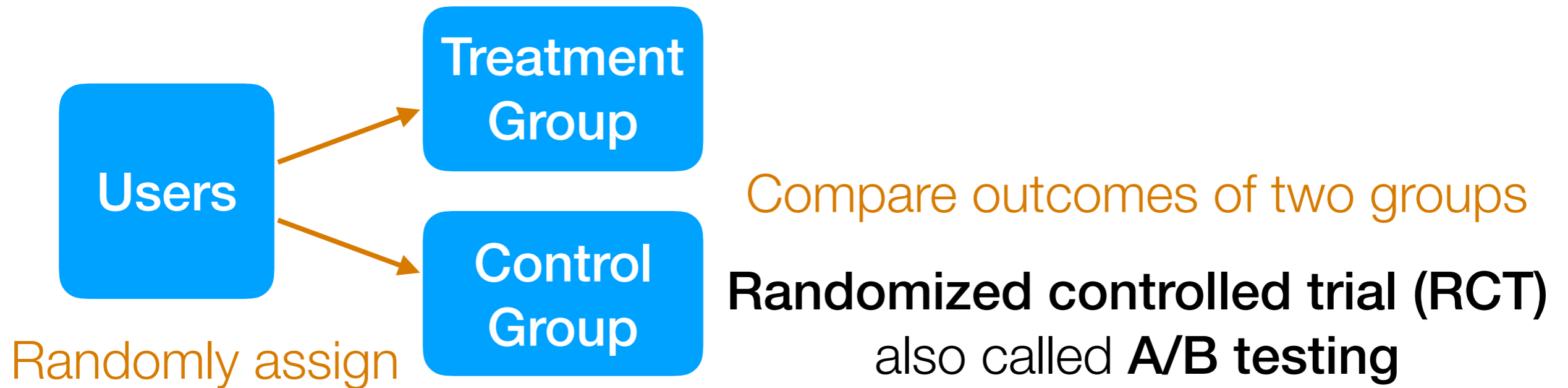
Back then: coffee drinkers also tended to smoke more than non-coffee drinkers (smoking is a **confounding variable**)

To establish causality, groups getting different treatments need to appear similar so that the only difference is the treatment

Image source: George Chen

# Establishing Causality

If you control data collection



Example: figure out webpage layout to maximize revenue (Amazon)

Example: figure out how to present educational material to improve learning (Khan Academy)

If you do not control data collection

In general: *not* obvious establishing what caused what



# 95-865

## Part I: Exploratory data analysis

*Identify structure present in “unstructured” data*

- Frequency and co-occurrence analysis *Basic probability & statistics*
- Visualizing high-dimensional data/dimensionality reduction
- Clustering
- Topic modeling (a special kind of clustering)

## Part II: Predictive data analysis

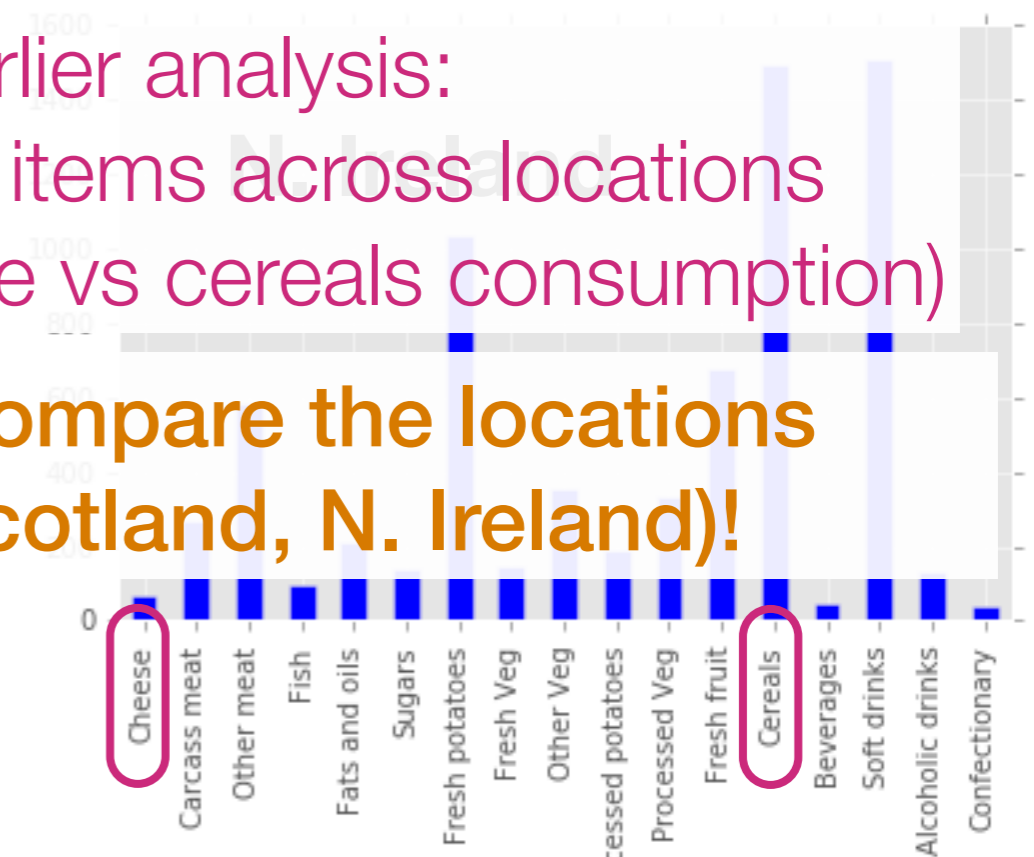
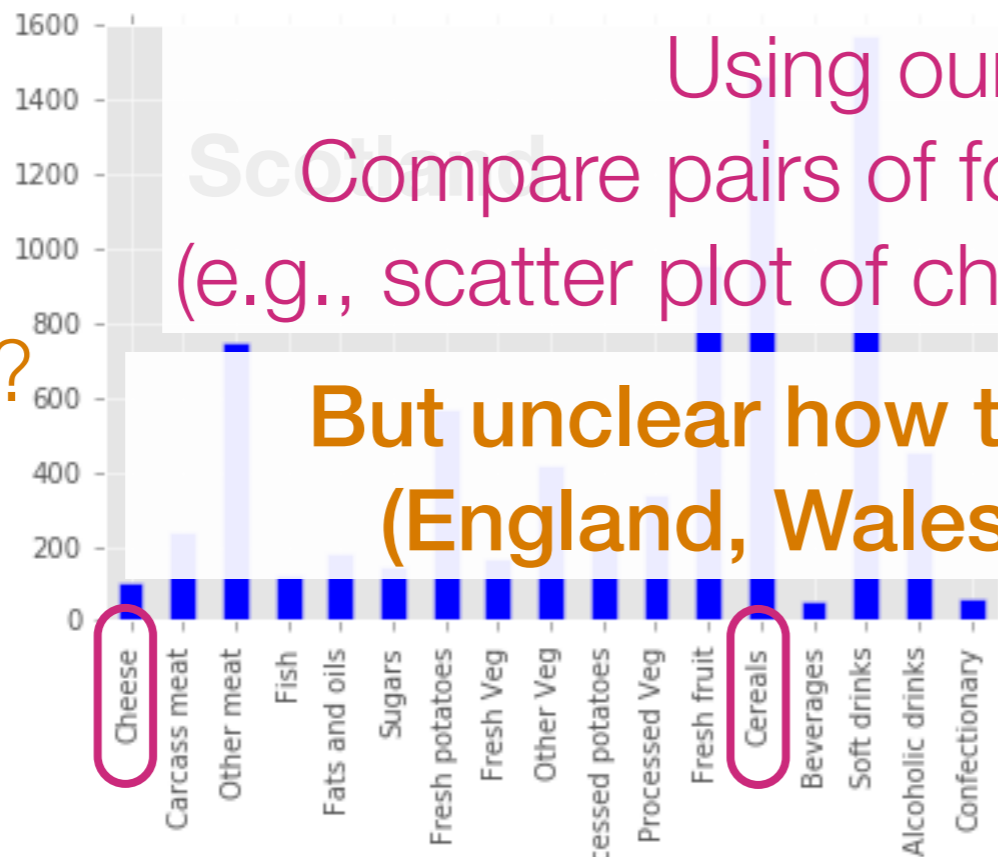
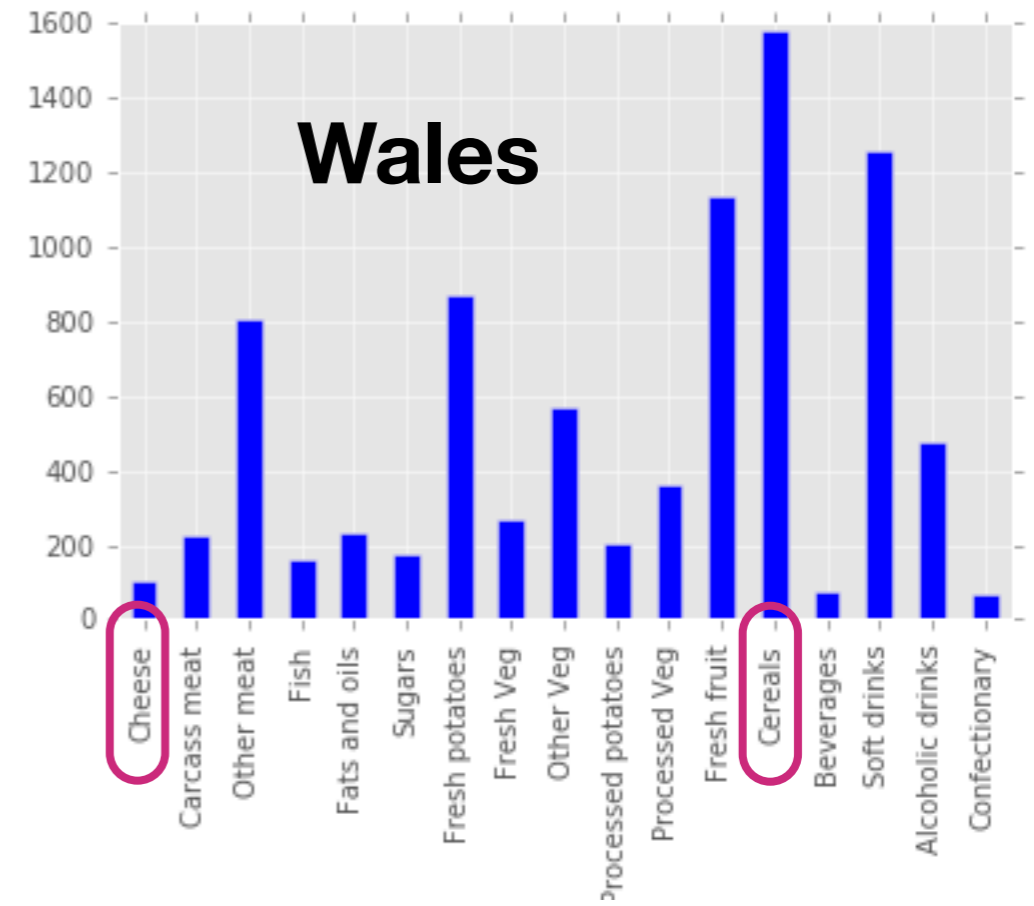
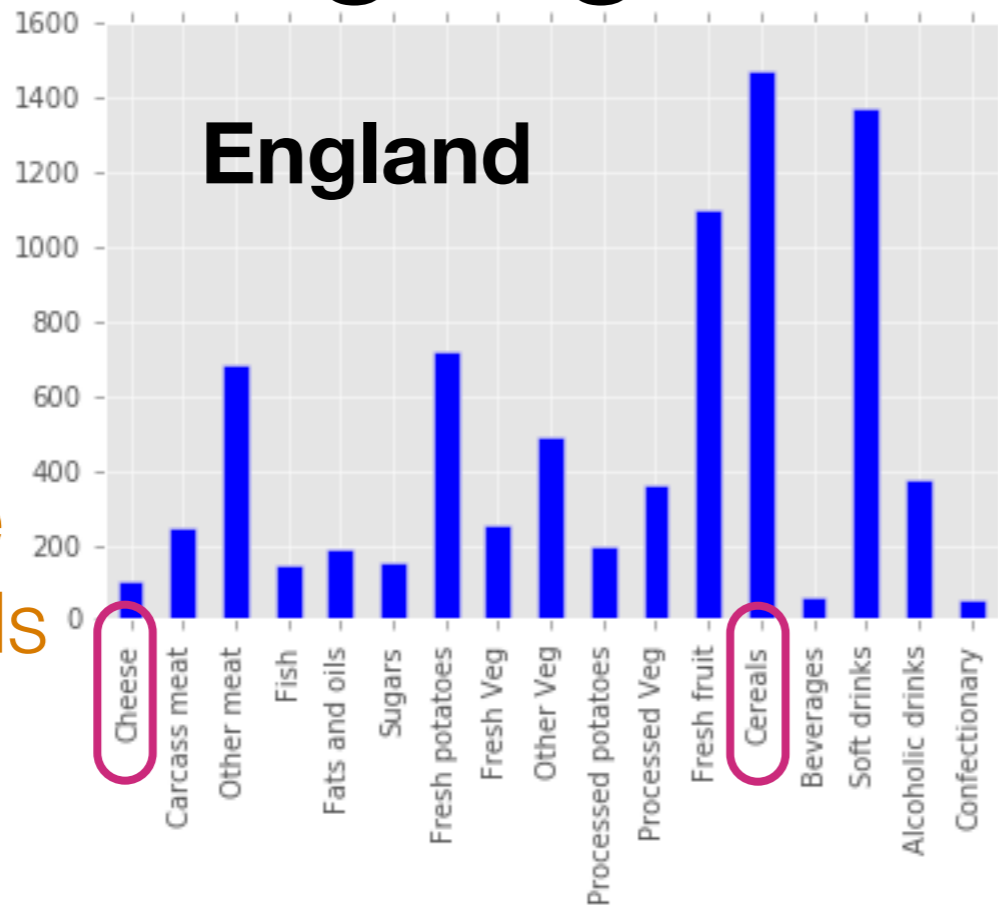
*Make predictions using structure found in Part I*

- Classical classification methods
- Neural nets and deep learning for analyzing images and text

# Visualizing High-Dimensional Vectors

The next two examples are drawn from:  
<http://setosa.io/ev/principal-component-analysis/>

# Visualizing High-Dimensional Vectors



Imagine we had hundreds of these

How to visualize these for comparison?

Using our earlier analysis:  
Compare pairs of food items across locations (e.g., scatter plot of cheese vs cereals consumption)

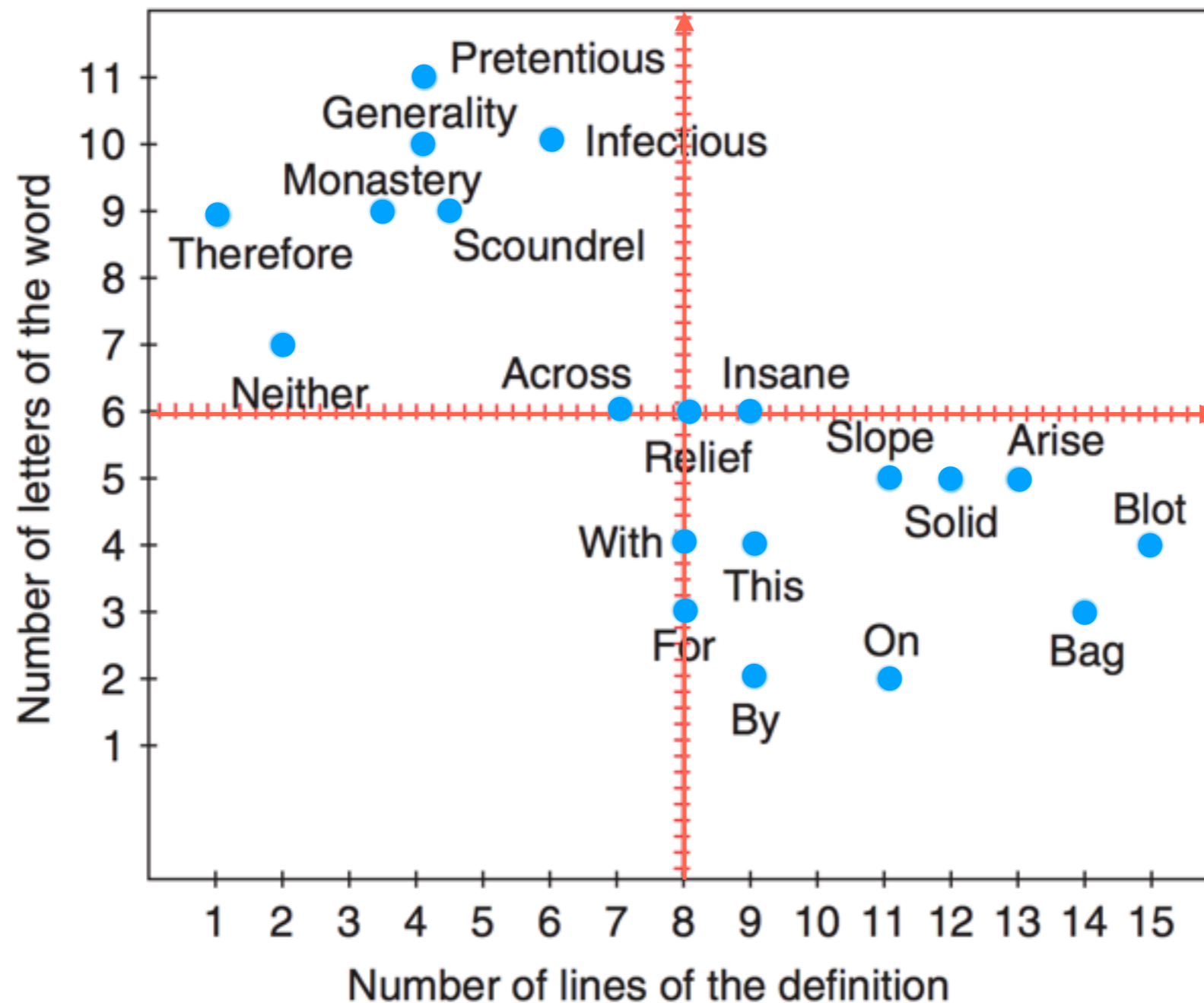
But unclear how to compare the locations (England, Wales, Scotland, N. Ireland)!

**The issue is that as humans  
we can only really visualize  
up to 3 dimensions easily**

Goal: Somehow reduce the dimensionality of the data  
preferably to 1, 2, or 3

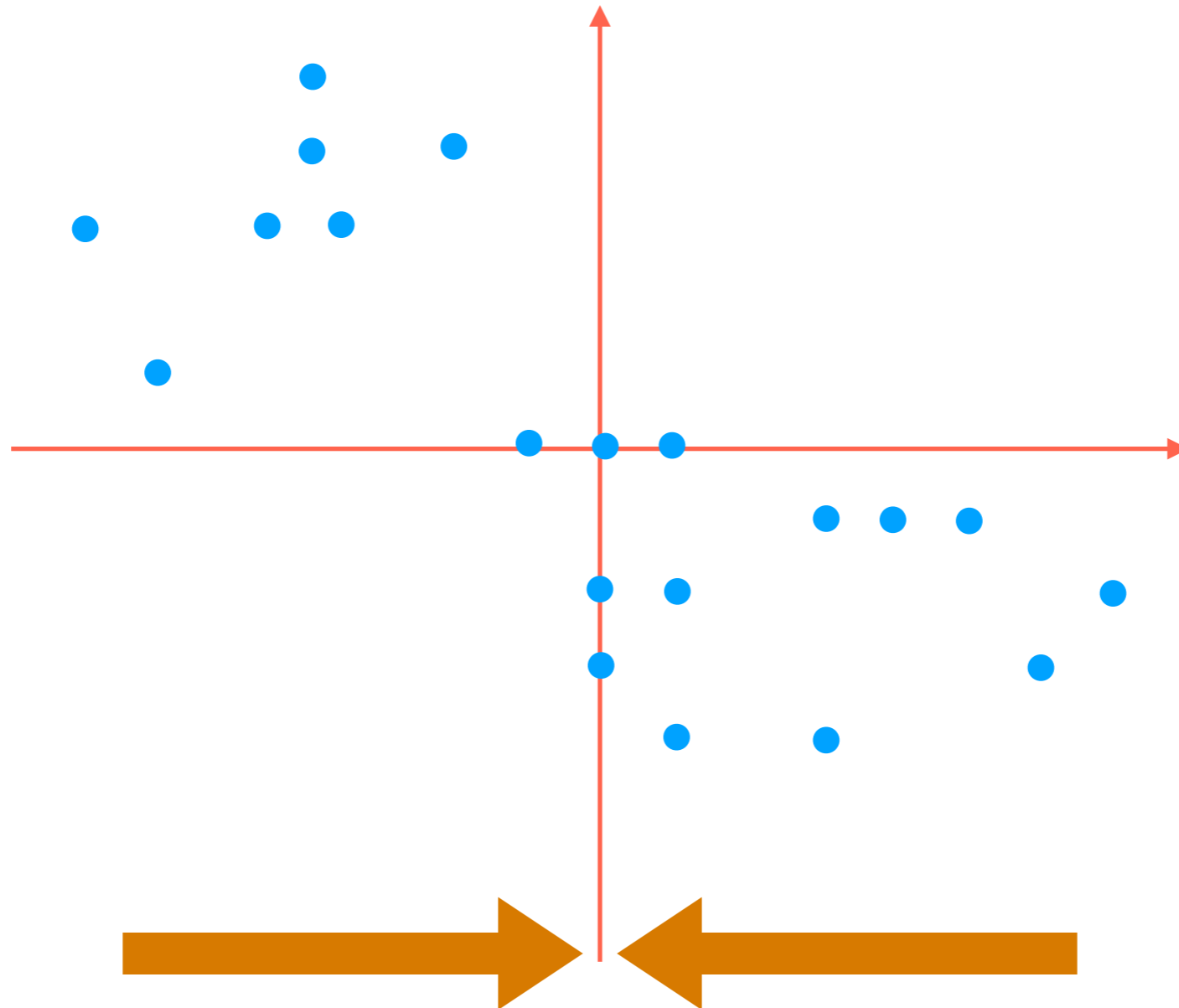
# Principal Component Analysis (PCA)

How to project 2D data down to 1D?



# Principal Component Analysis (PCA)

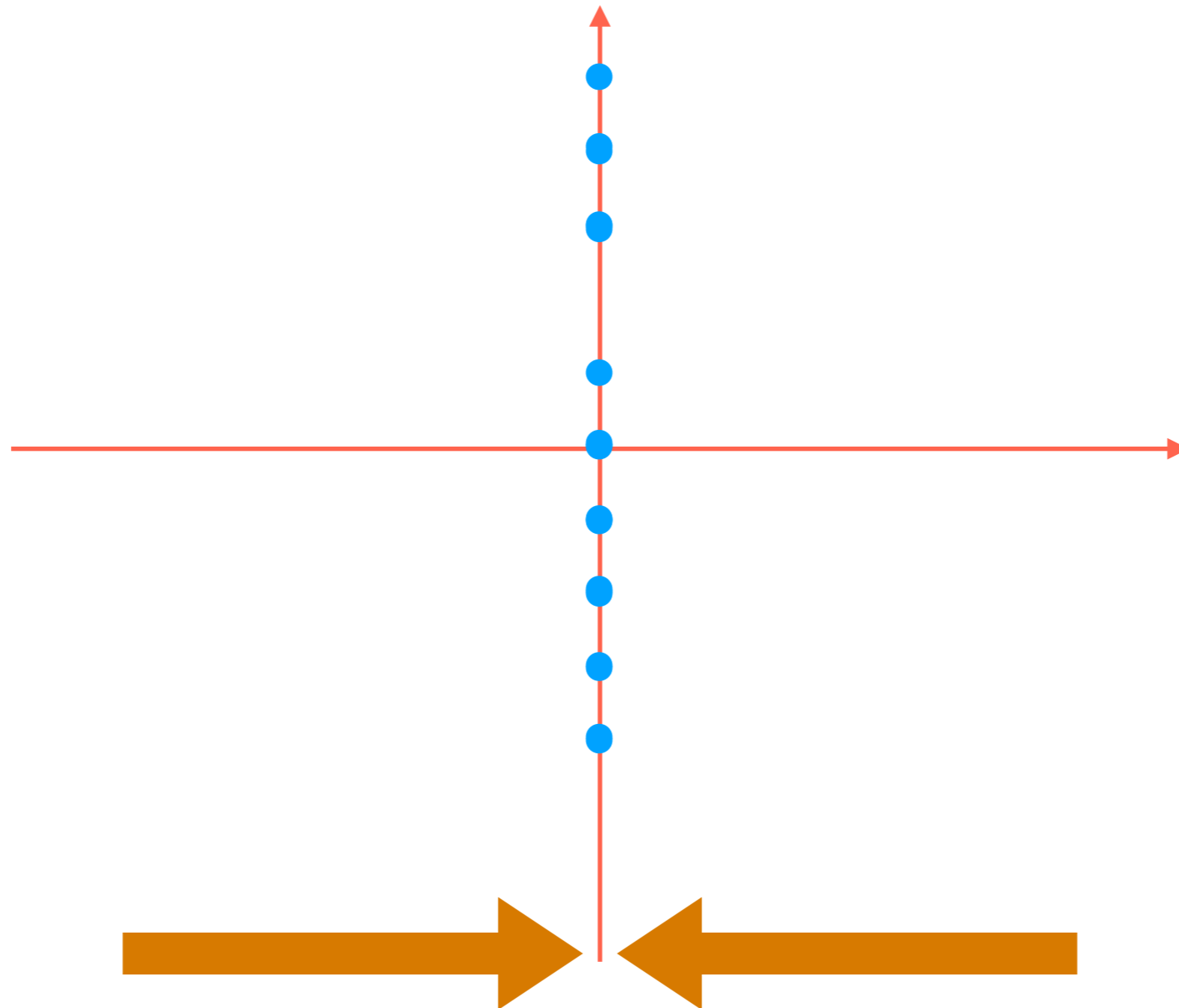
How to project 2D data down to 1D?



Simplest thing to try: flatten to one of the red axes

# Principal Component Analysis (PCA)

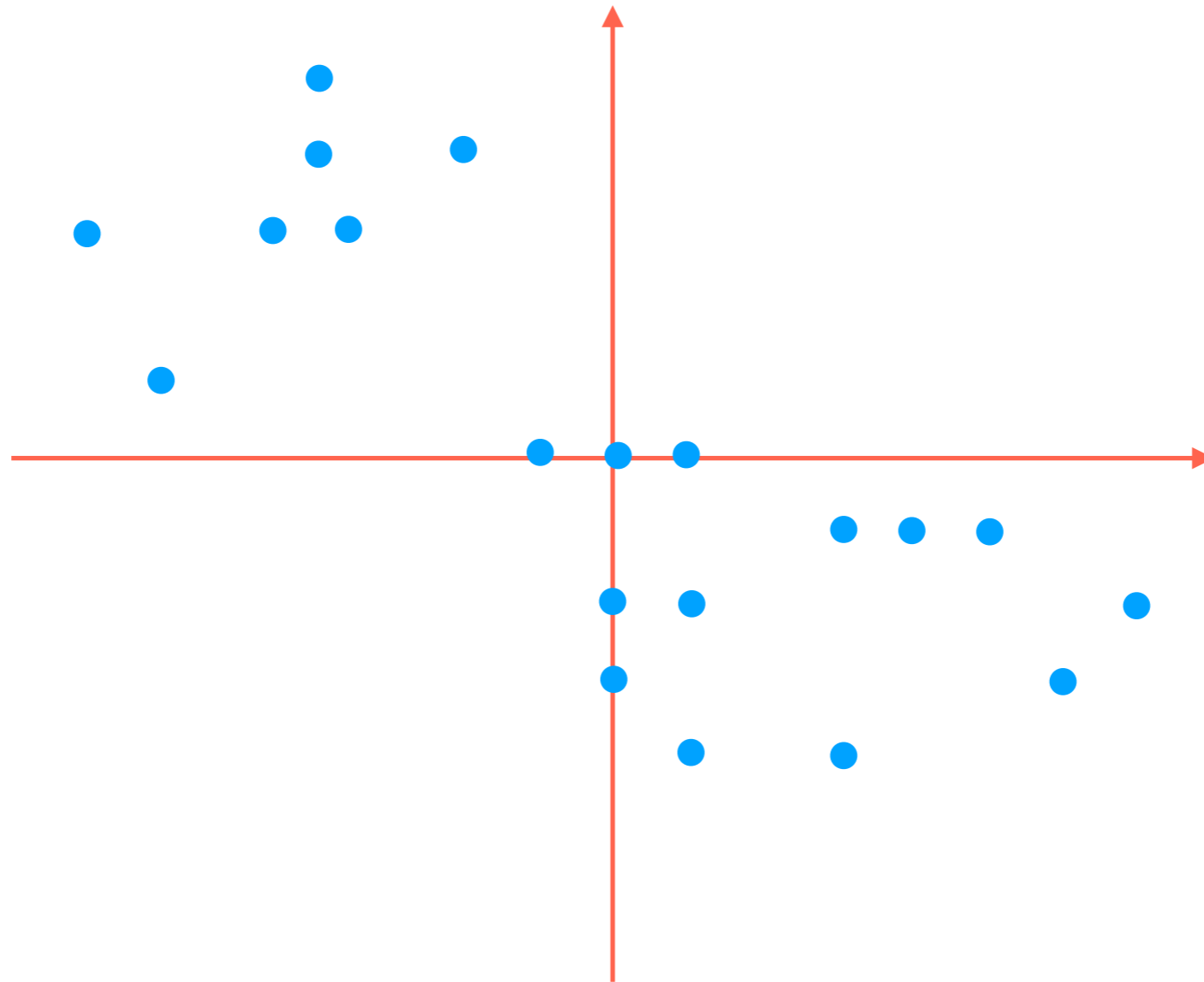
How to project 2D data down to 1D?



Simplest thing to try: flatten to one of the red axes  
(We could of course flatten to the other red axis)

# Principal Component Analysis (PCA)

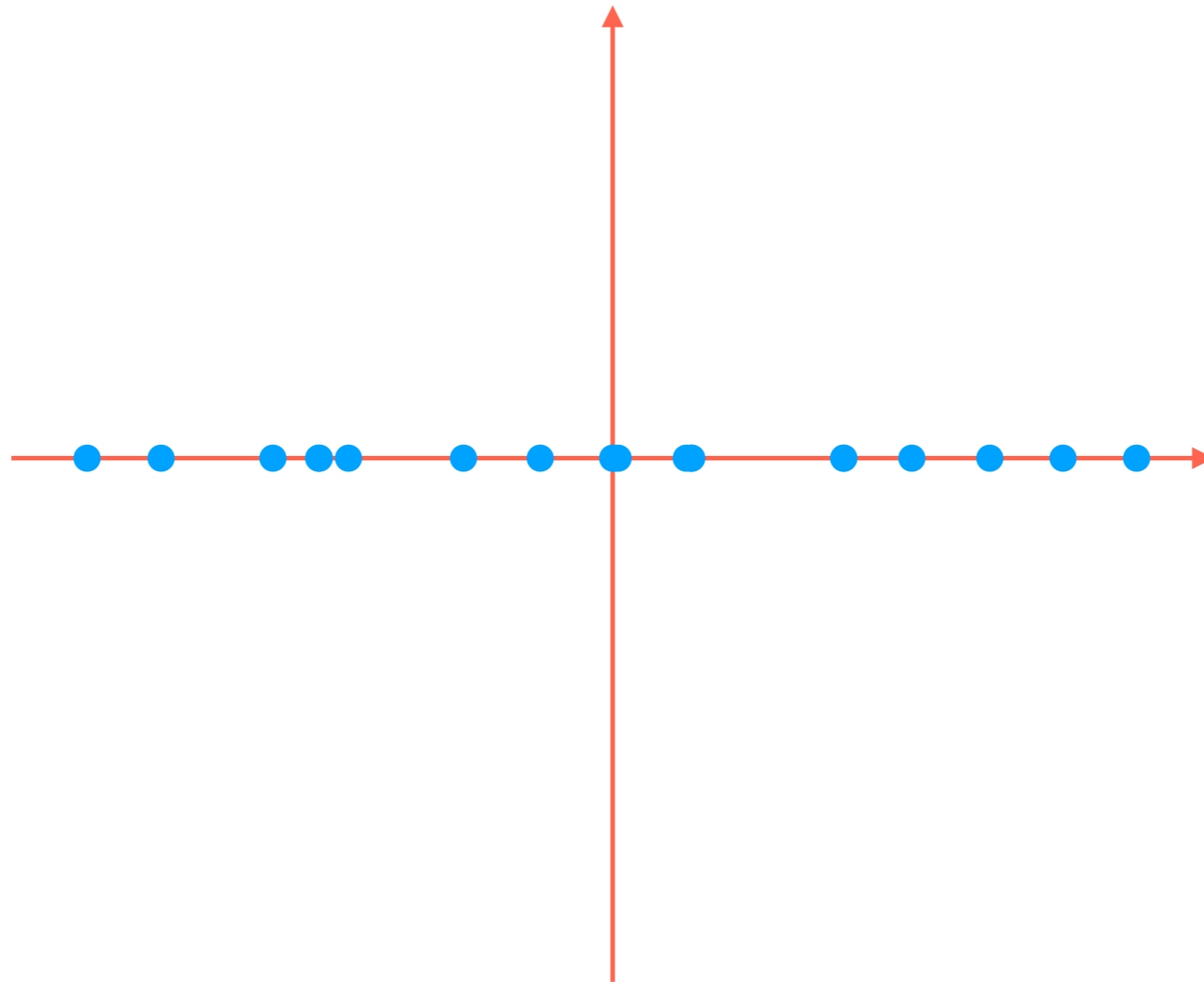
How to project 2D data down to 1D?





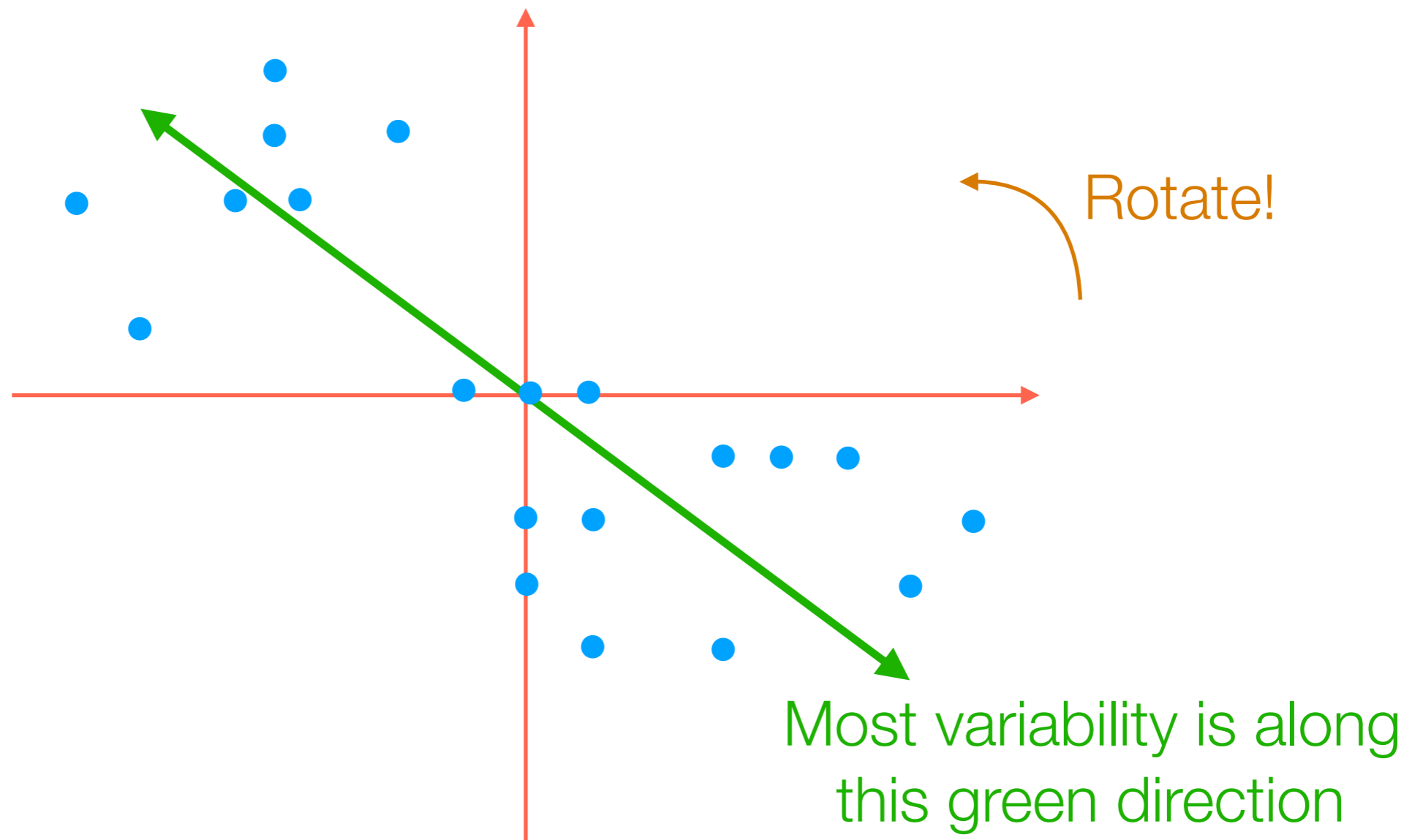
# Principal Component Analysis (PCA)

How to project 2D data down to 1D?



# Principal Component Analysis (PCA)

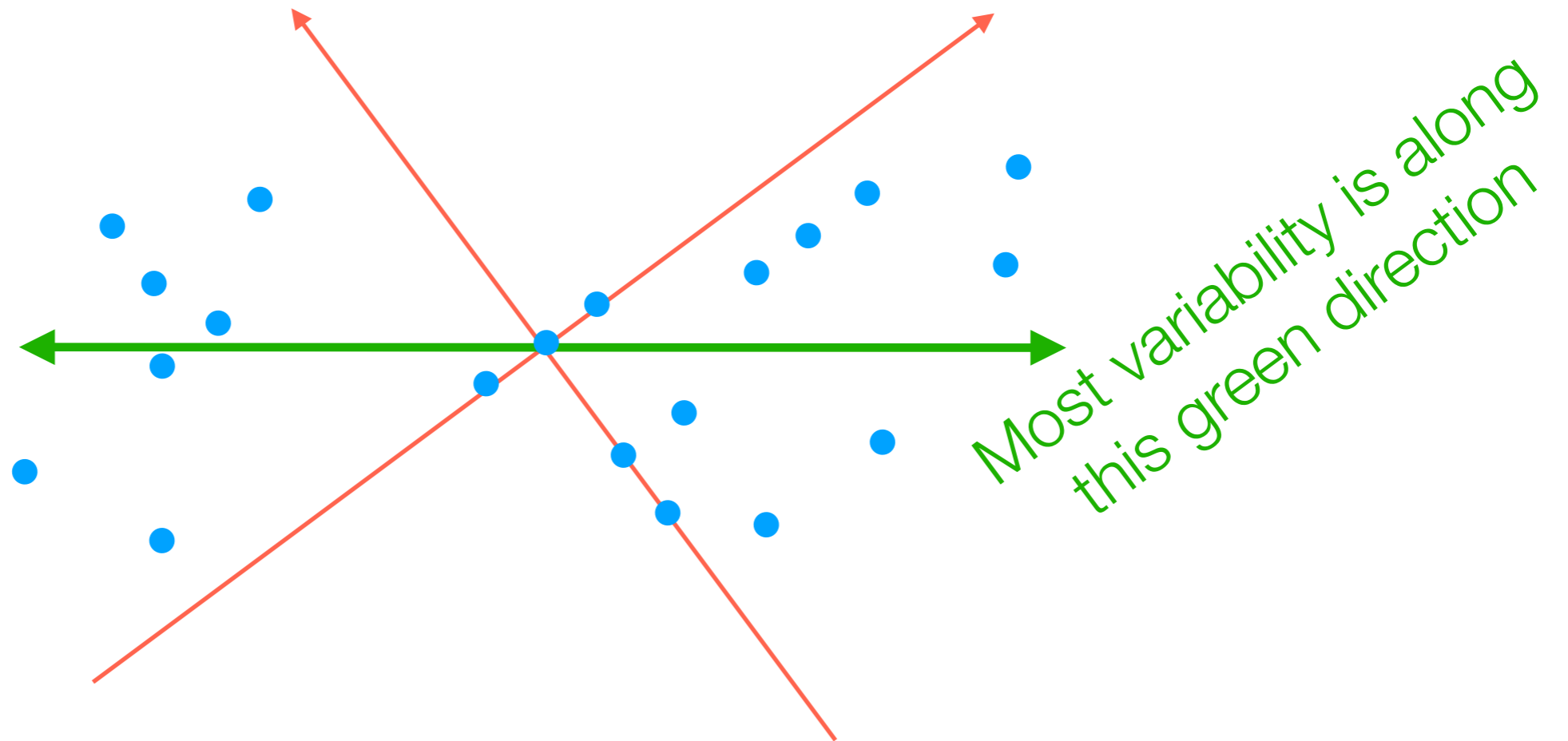
How to project 2D data down to 1D?



But notice that most of the variability in the data is *not* aligned with the red axes!

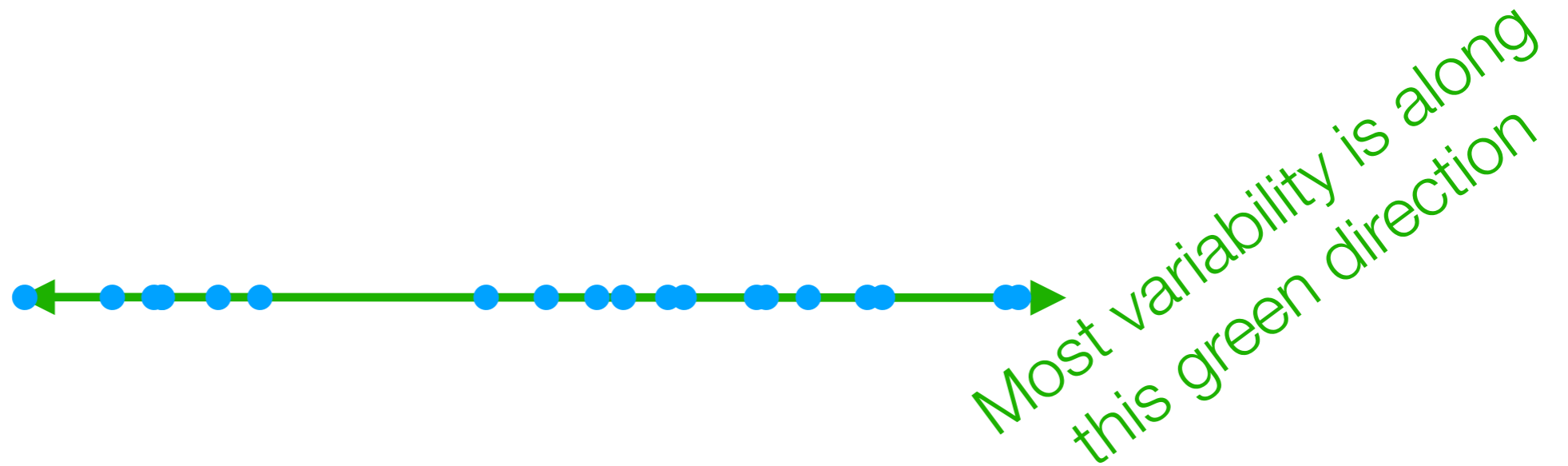
# Principal Component Analysis (PCA)

How to project 2D data down to 1D?



# Principal Component Analysis (PCA)

How to project 2D data down to 1D?

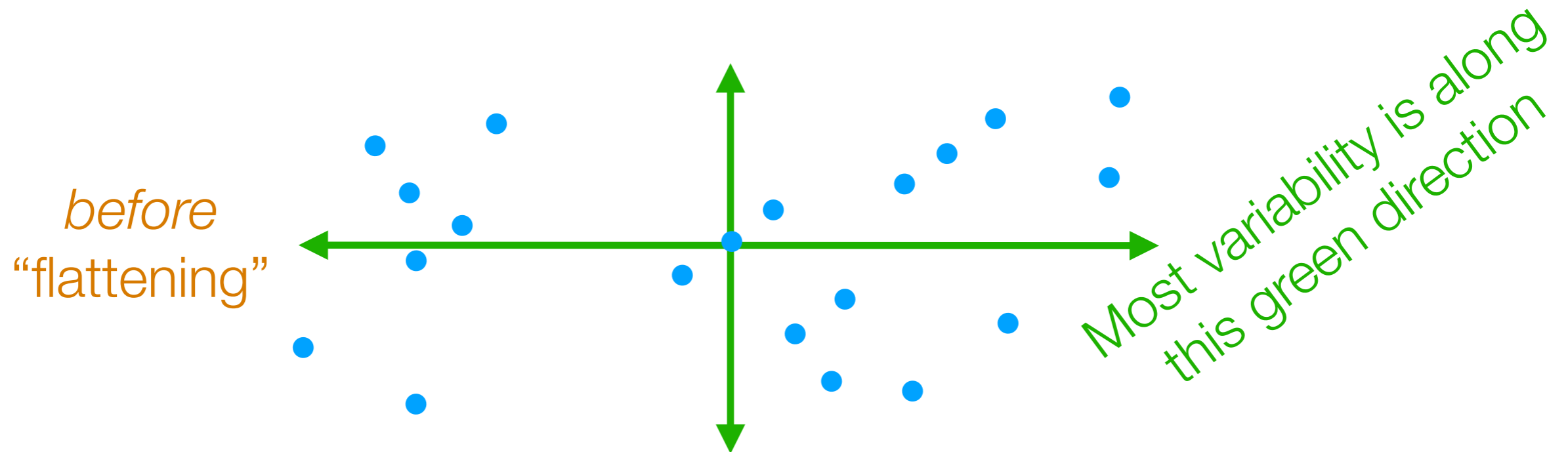


The idea of PCA actually works for 2D  $\rightarrow$  2D as well (and just involves rotating, and not “flattening” the data)

# Principal Component Analysis (PCA)

~~How to project 2D data down to 1D?~~

How to rotate 2D data so 1st axis has most variance



The idea of PCA actually works for  $2D \rightarrow 2D$  as well  
(and just involves rotating, and not "flattening" the data)

2nd green axis chosen to be  $90^\circ$  ("orthogonal") from first green axis

# Principal Component Analysis (PCA)

- Finds top  $k$  orthogonal directions that explain the most variance in the data
  - 1st component: explains most variance along 1 dimension
  - 2nd component: explains most of remaining variance along next dimension that is orthogonal to 1st dimension
  - ...
- “Flatten” data to the top  $k$  dimensions to get lower dimensional representation (if  $k <$  original dimension)

# Principal Component Analysis (PCA)

3D example from:

<http://setosa.io/ev/principal-component-analysis/>

# Principal Component Analysis (PCA)

Demo

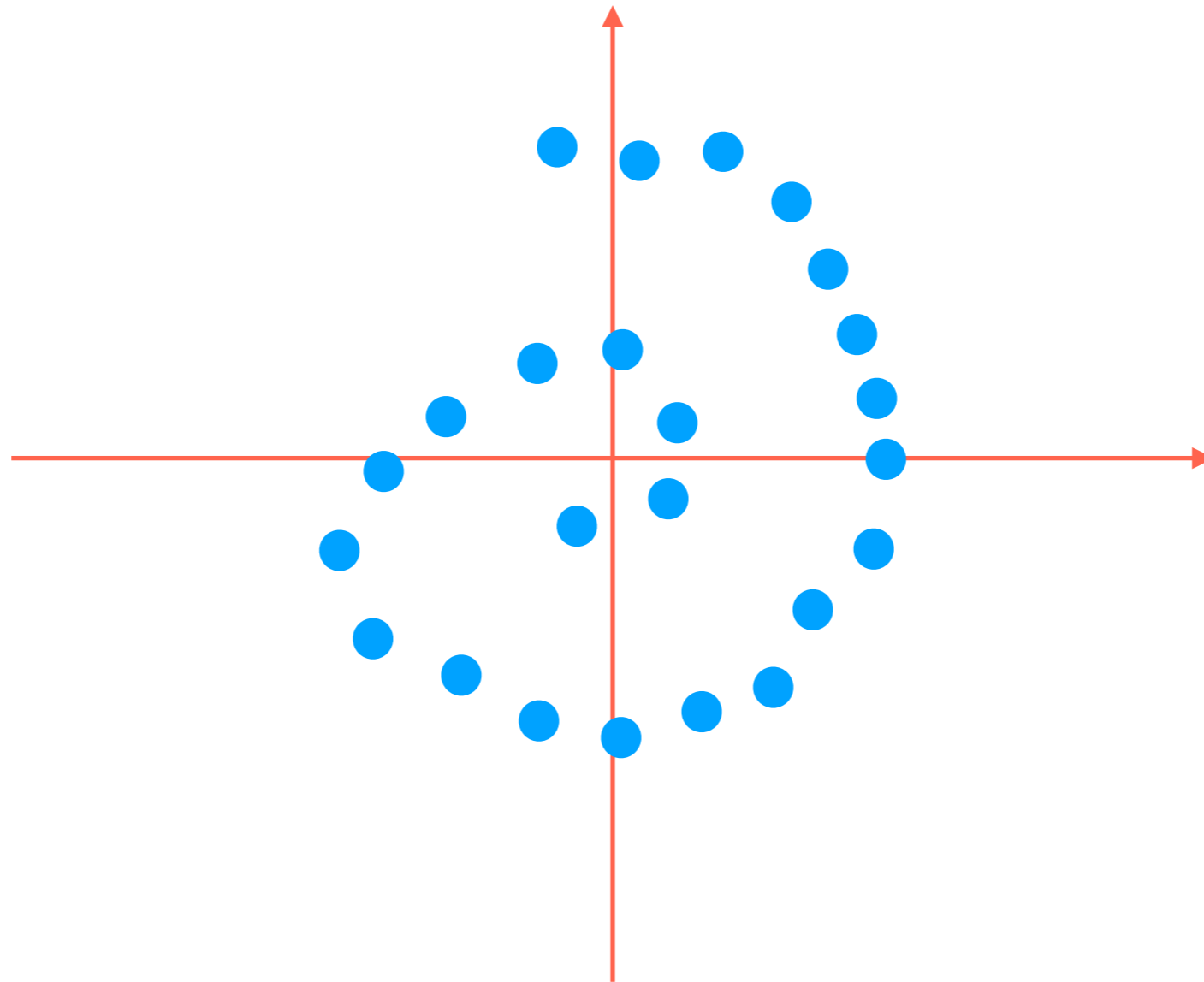


**PCA reorients data so axes explain variance in “decreasing order”**  
**→ can “flatten” (*project*) data onto a few axes that captures most variance**

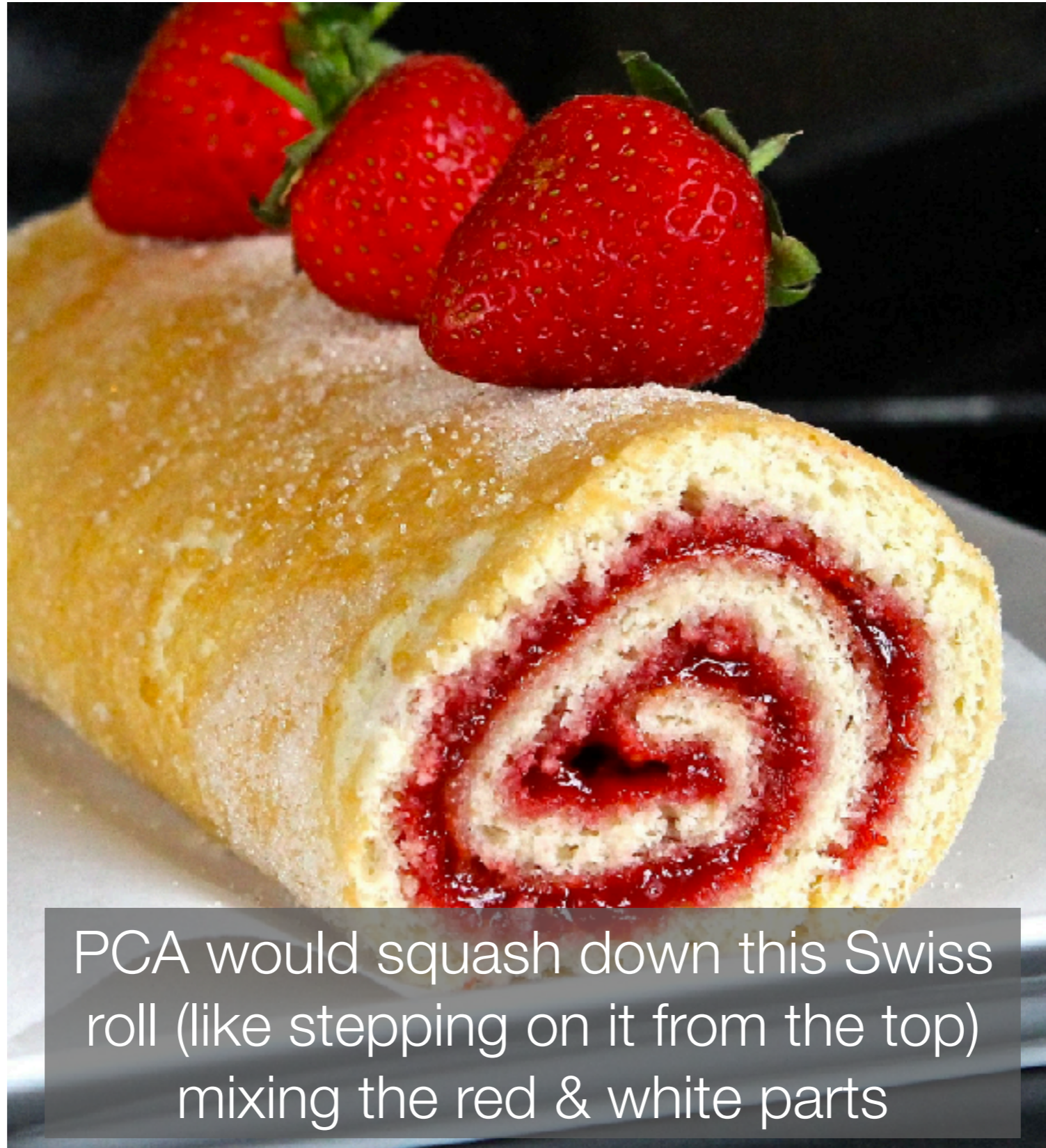


Image source: [http://4.bp.blogspot.com/-USQEgoh1jCU/VfncdNOETcl/AAAAAAAAAGp8/Hea8UtE\\_1c0/s1600/Blog%2B1%2BIMG\\_1821.jpg](http://4.bp.blogspot.com/-USQEgoh1jCU/VfncdNOETcl/AAAAAAAAAGp8/Hea8UtE_1c0/s1600/Blog%2B1%2BIMG_1821.jpg)

# 2D Swiss Roll



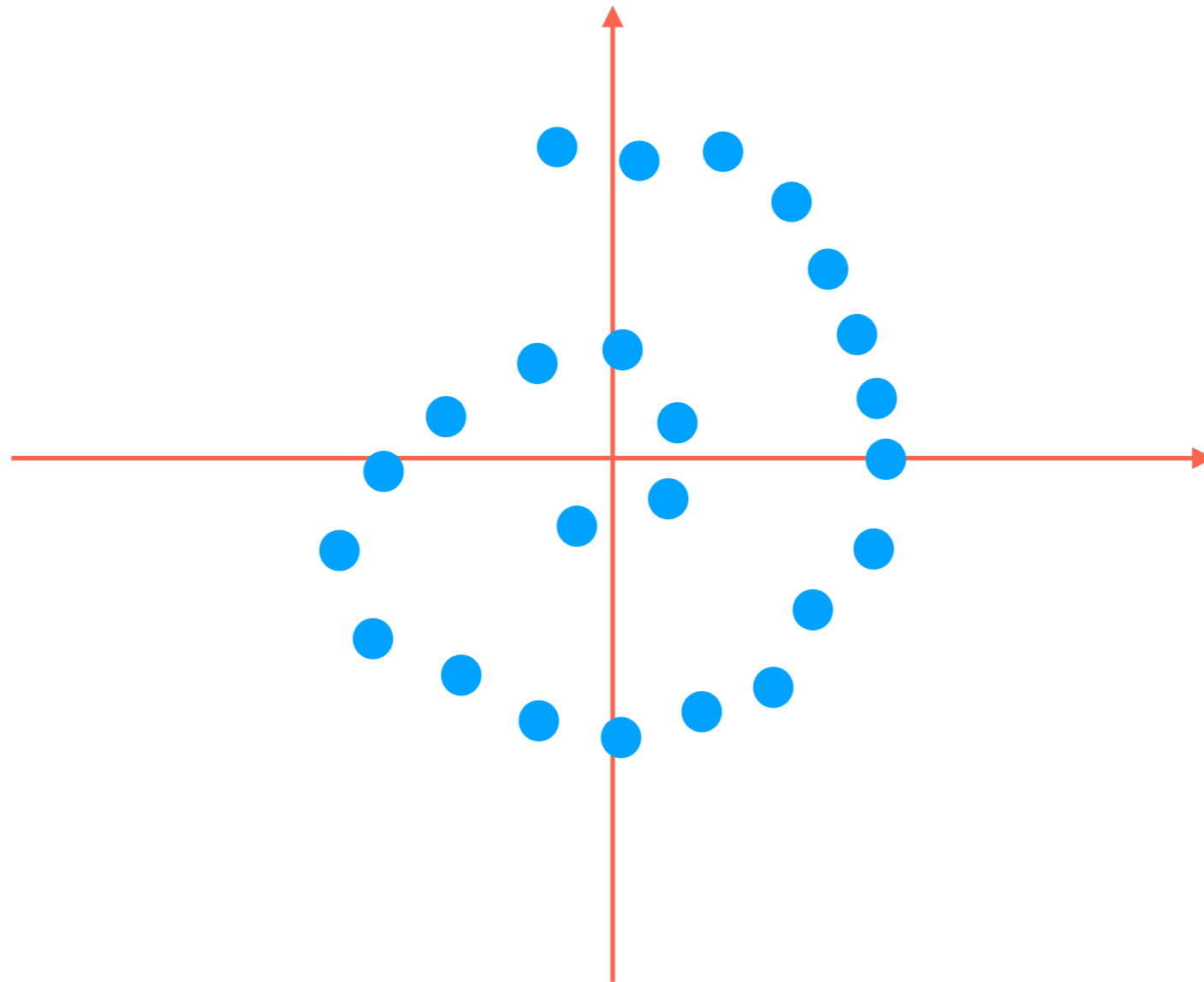
PCA would just flatten this thing and  
*lose the information that the data actually  
lives on a 1D line that has been curved!*



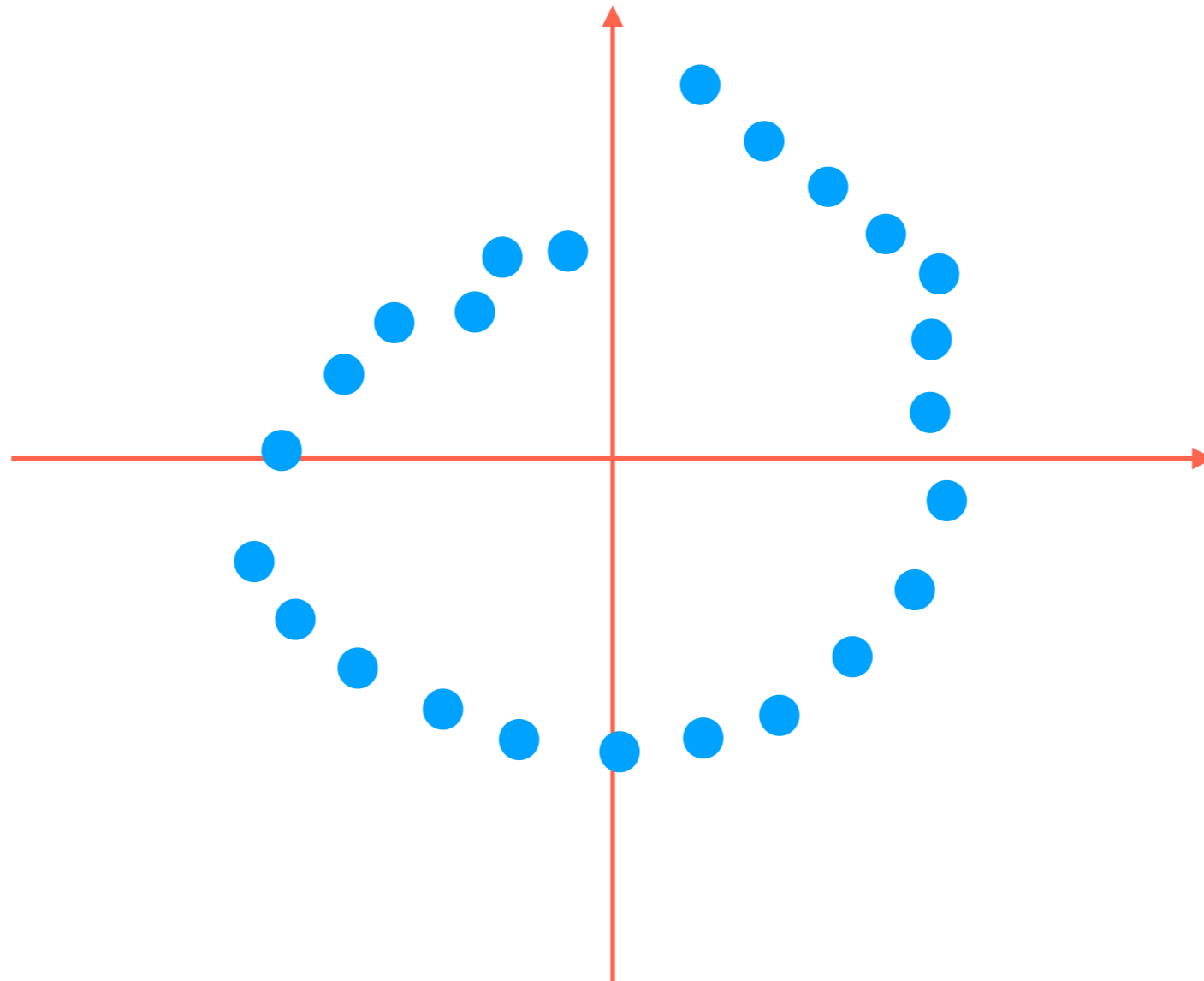
PCA would squash down this Swiss roll (like stepping on it from the top) mixing the red & white parts

Image source: [http://4.bp.blogspot.com/-USQEgoh1jCU/VfncdNOETcl/AAAAAAAAAGp8/Hea8UtE\\_1c0/s1600/Blog%2B1%2BIMG\\_1821.jpg](http://4.bp.blogspot.com/-USQEgoh1jCU/VfncdNOETcl/AAAAAAAAAGp8/Hea8UtE_1c0/s1600/Blog%2B1%2BIMG_1821.jpg)

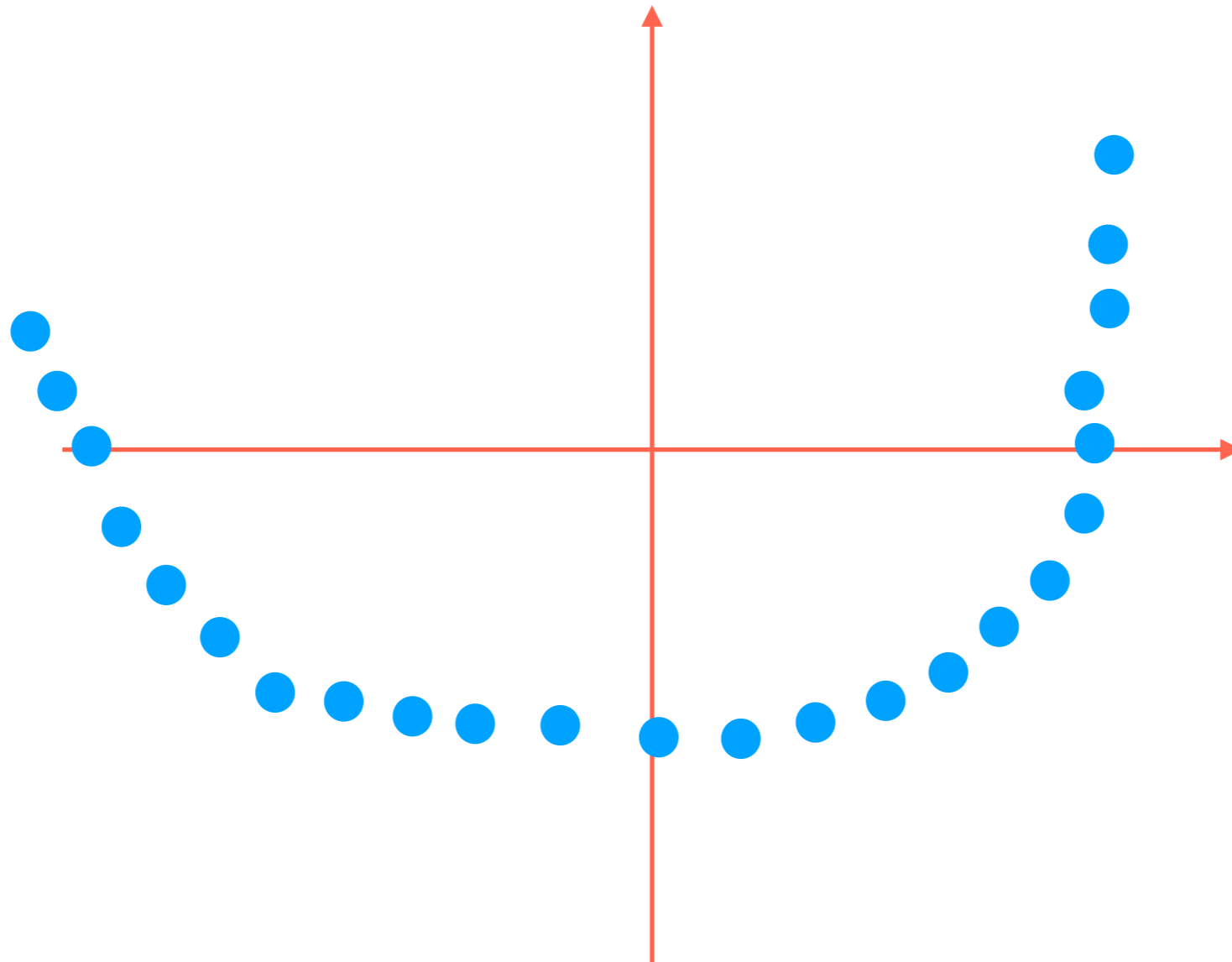
# 2D Swiss Roll



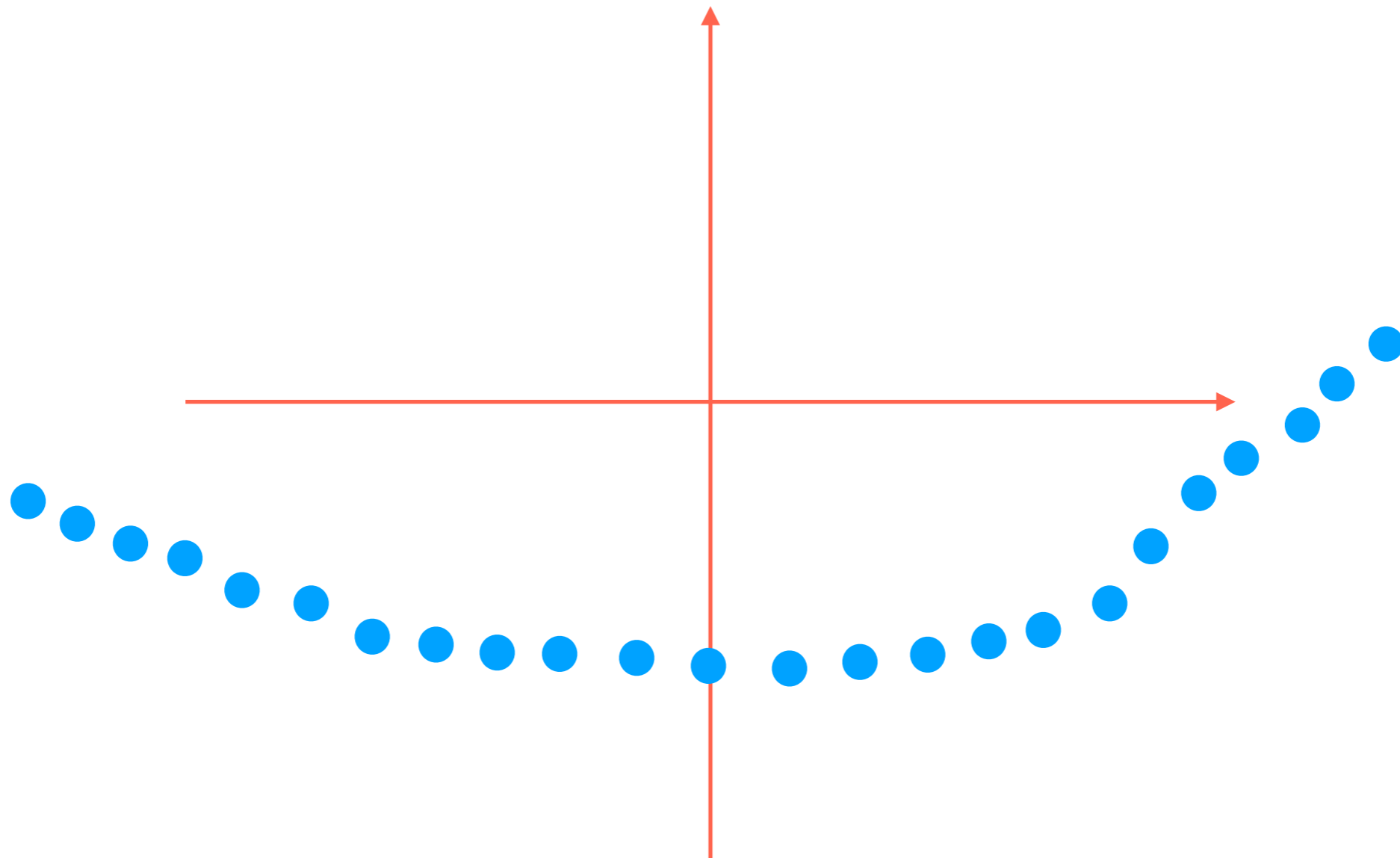
# 2D Swiss Roll



# 2D Swiss Roll

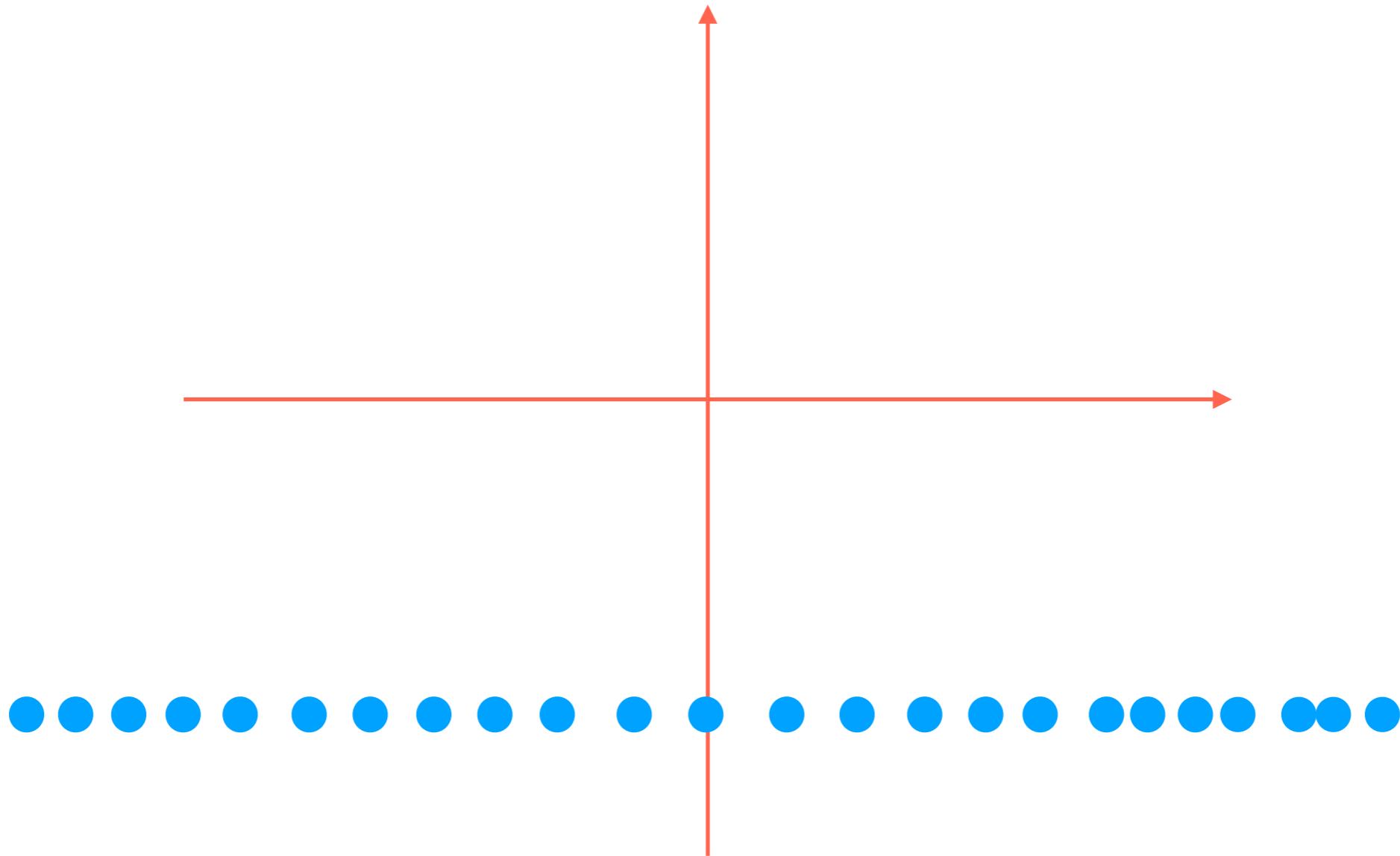


# 2D Swiss Roll





# 2D Swiss Roll

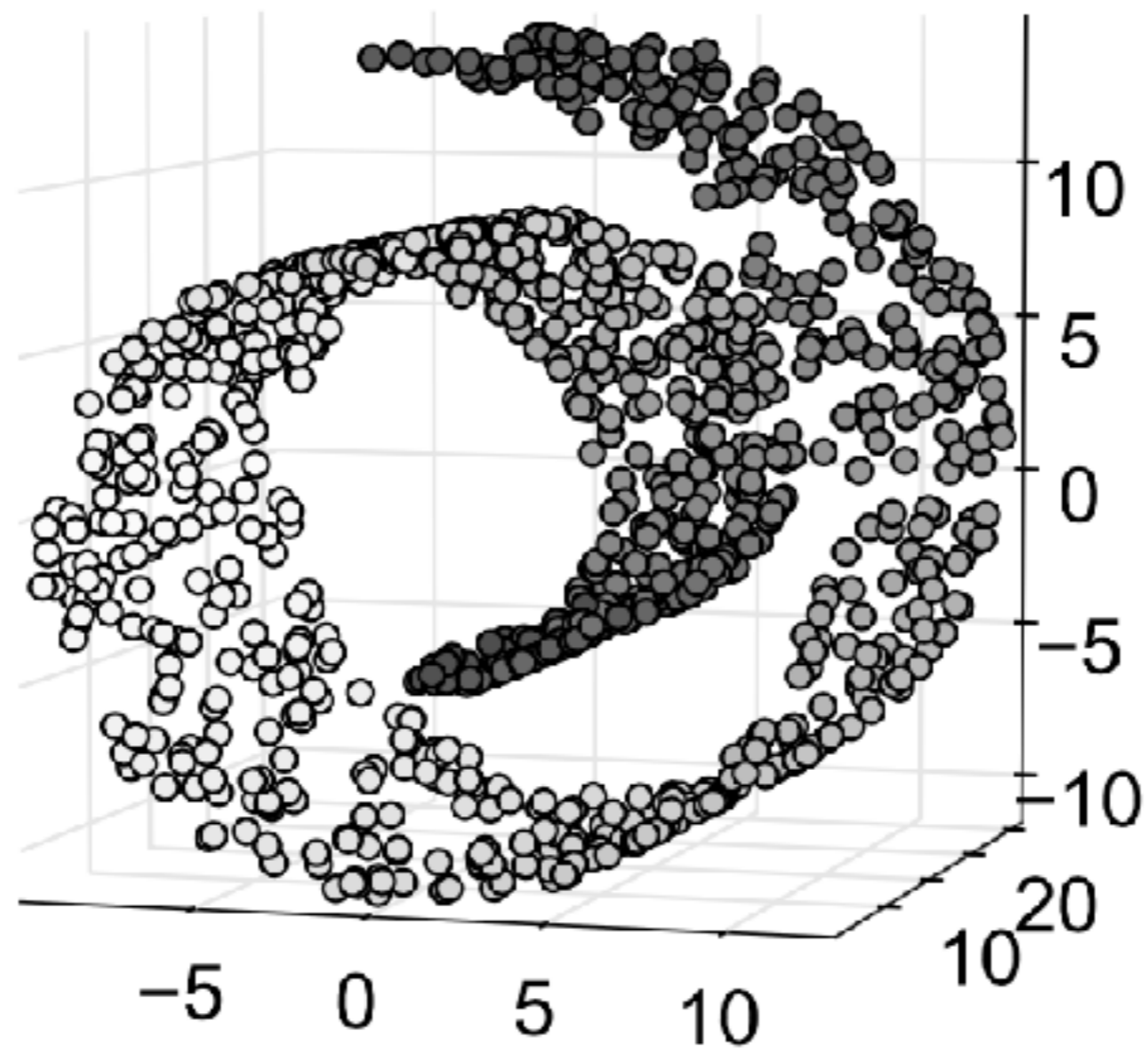


# 2D Swiss Roll



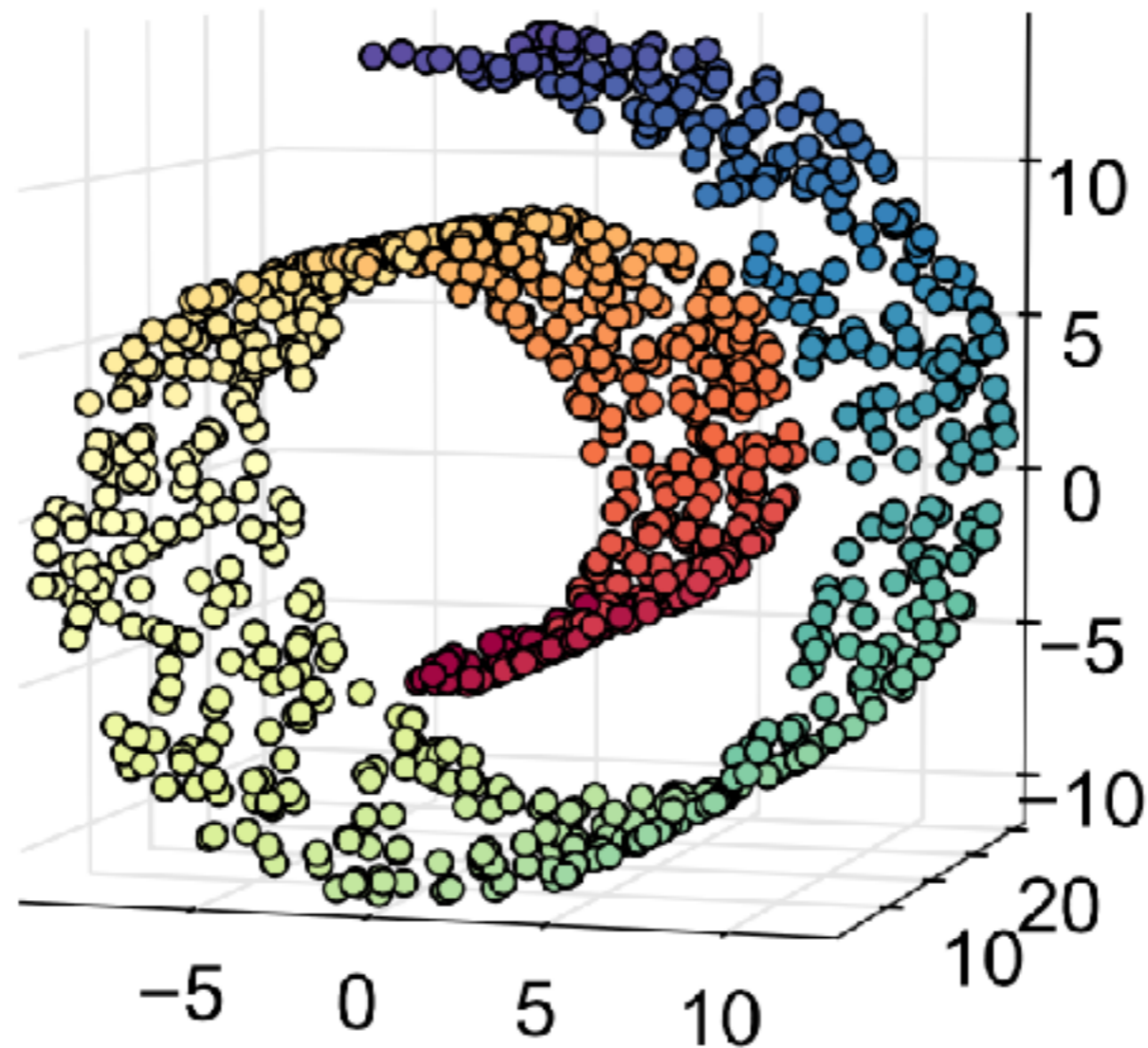
This is the desired result

# 3D Swiss Roll



Projecting down to any 2D plane puts points that are far apart close together!

# 3D Swiss Roll

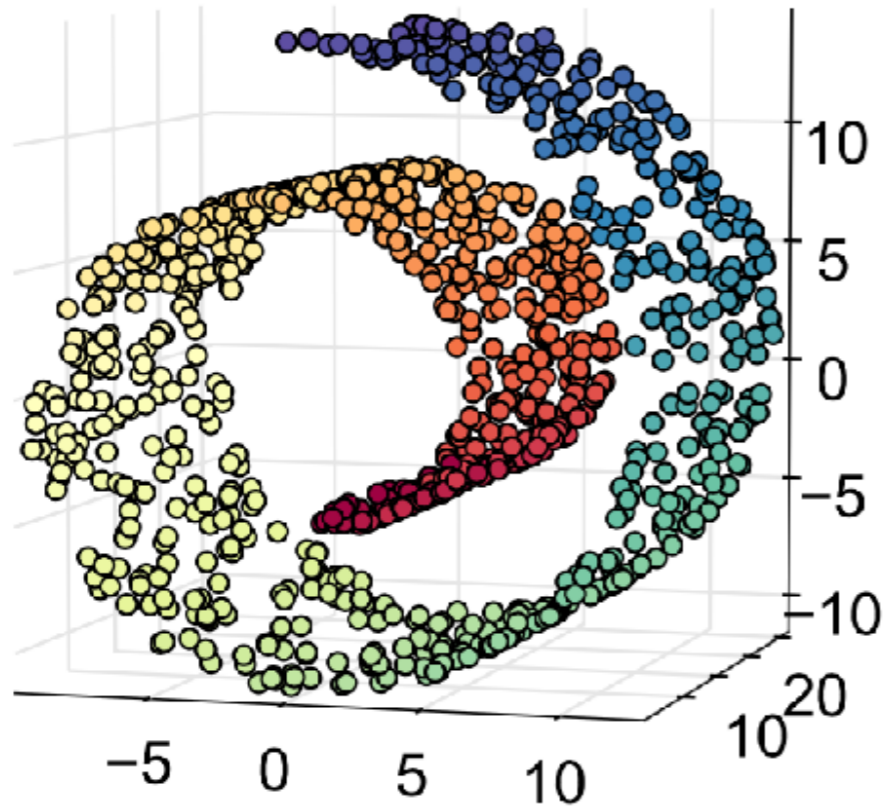


Projecting down to any 2D plane puts points that are far apart close together!

Goal: Low-dimensional representation where similar colored points are near each other (we don't actually get to see the colors)

# Manifold Learning

- Nonlinear dimensionality reduction (in contrast to PCA which is linear)
- Find low-dimensional “manifold” that the data live on



Basic idea of a manifold:

1. Zoom in on any point (say,  $x$ )
2. The points near  $x$  look like they're in a lower-dimensional Euclidean space (e.g., a 2D plane in Swiss roll)

# Do Data Actually Live on Manifolds?

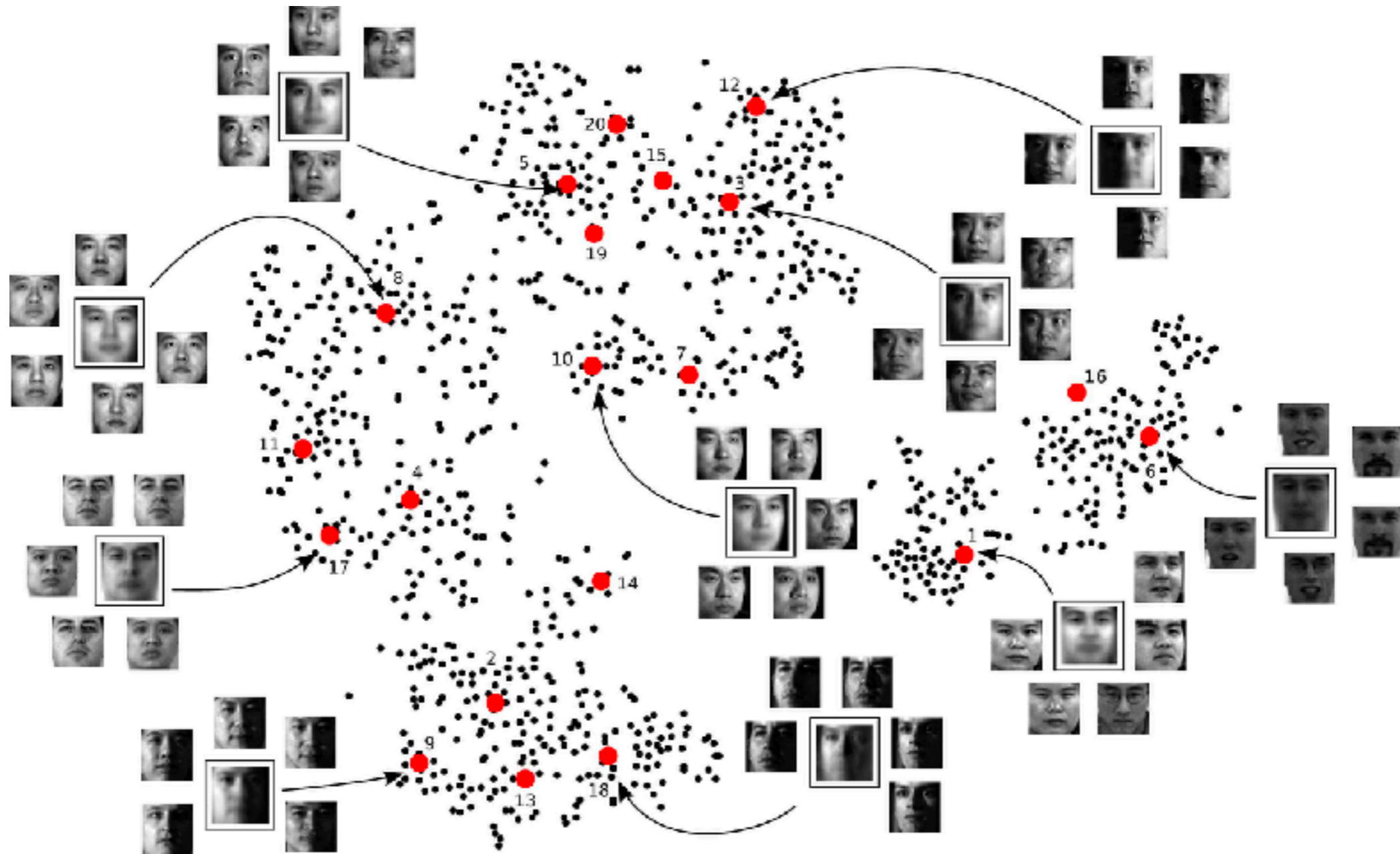


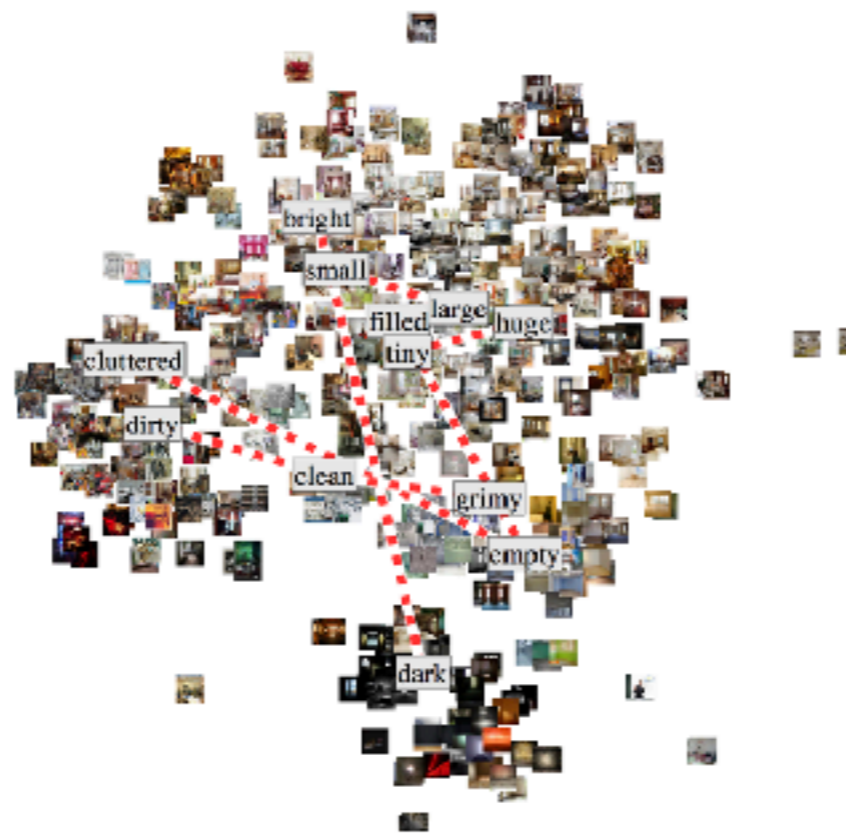
Image source: <http://www.columbia.edu/~jwp2128/Images/faces.jpeg>

# Do Data Actually Live on Manifolds?

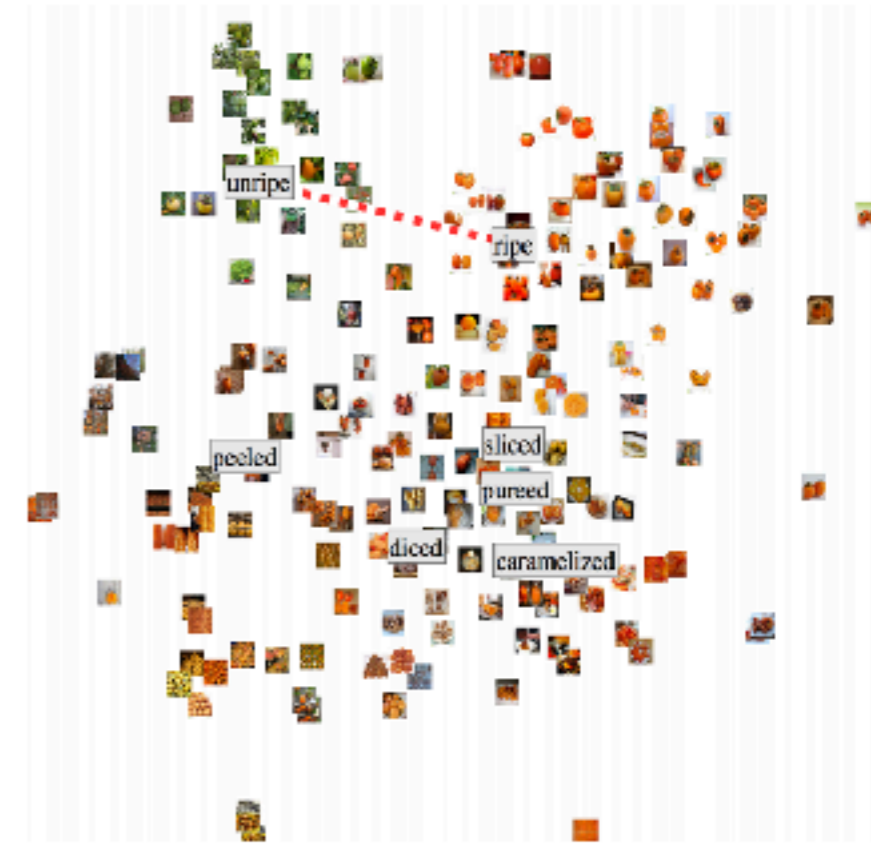
Fish



Room



Persimmon



Phillip Isola, Joseph Lim, Edward H. Adelson. Discovering States and Transformations in Image Collections. CVPR 2015.

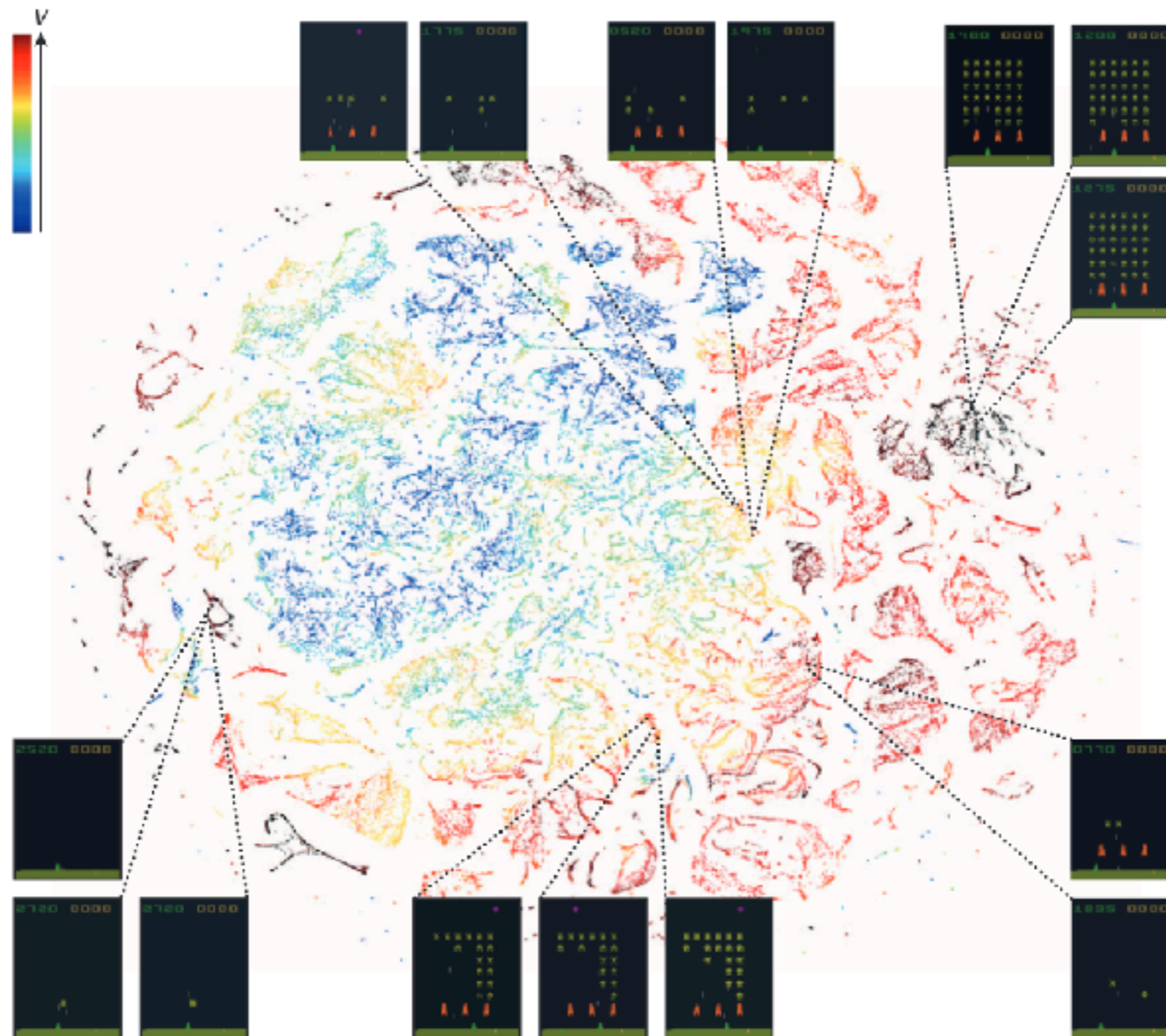
# Do Data Actually Live on Manifolds?



Image source: <http://www.adityathakker.com/wp-content/uploads/2017/06/word-embeddings-994x675.png>



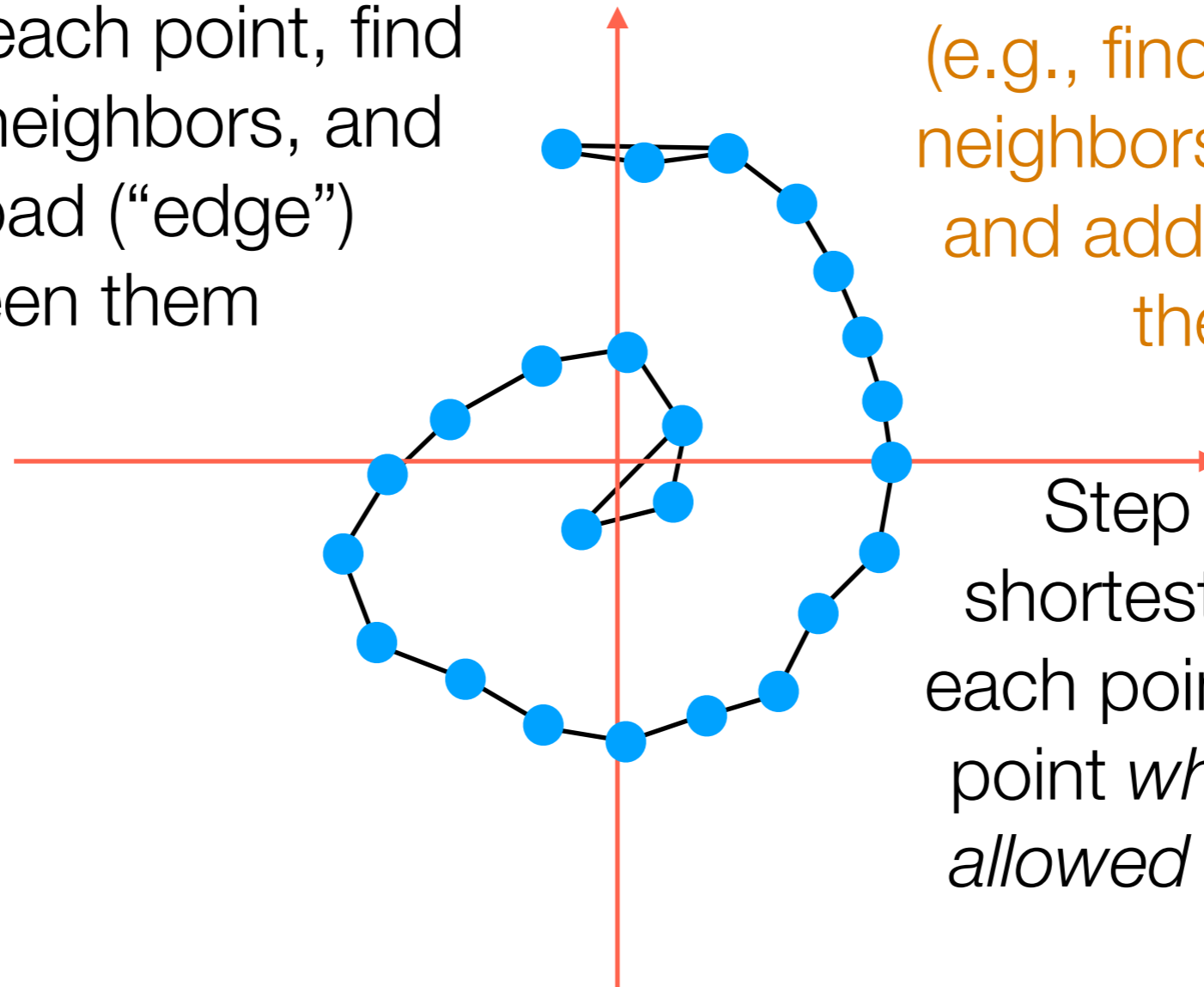
# Do Data Actually Live on Manifolds?



Mnih, Volodymyr, et al. Human-level control through deep reinforcement learning. Nature 2015.

# Manifold Learning with Isomap

Step 1: For each point, find its nearest neighbors, and build a road (“edge”) between them



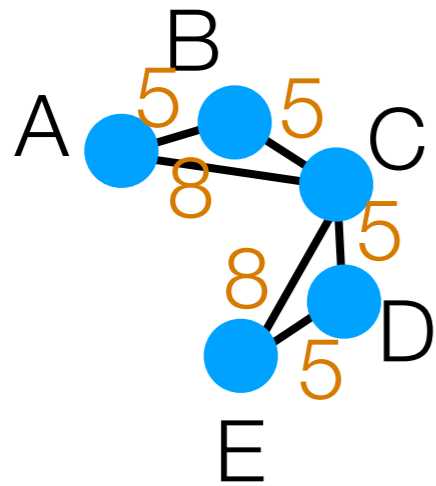
(e.g., find closest 2 neighbors per point and add edges to them)

Step 2: Compute shortest distance from each point to every other point *where you're only allowed to travel on the roads*

Step 3: It turns out that given all the distances between pairs of points, we can compute what the points should be (the algorithm for this is called *multidimensional scaling*)

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

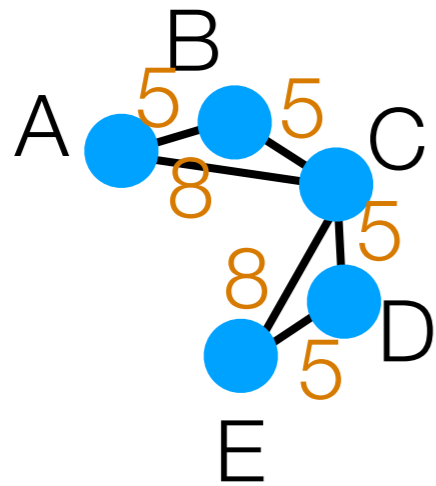
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A					
B					
C					
D					
E					

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

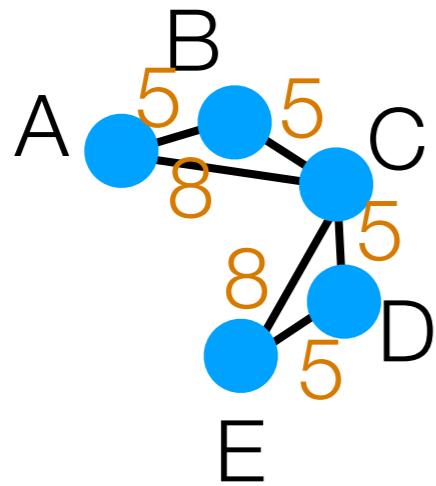
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0				
B		0			
C			0		
D				0	
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

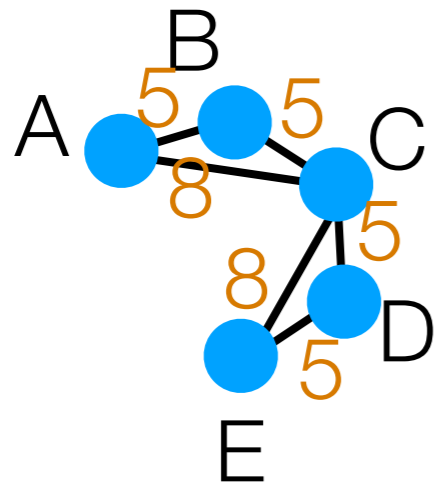
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5			
B		0	5		
C			0	5	
D				0	5
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

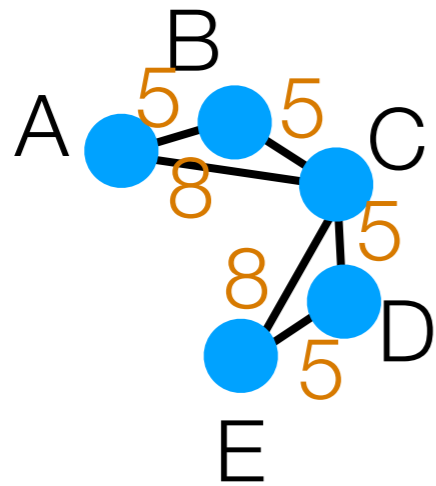
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8		
B		0	5		
C			0	5	
D				0	5
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

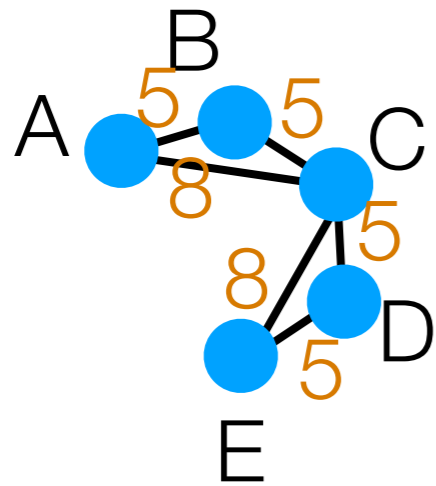
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	
B		0	5		
C			0	5	
D				0	5
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

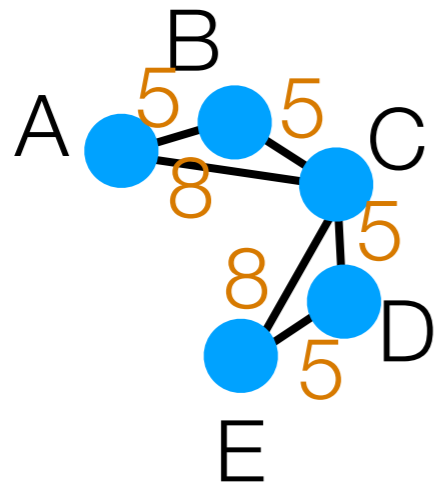
Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	16
B		0	5		
C			0	5	
D				0	5
E					0



# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

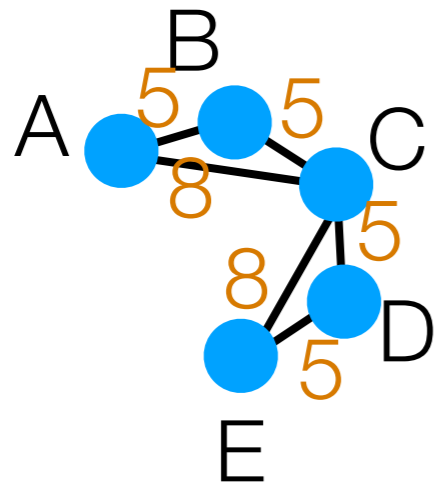
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	16
B		0	5	10	
C			0	5	
D				0	5
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

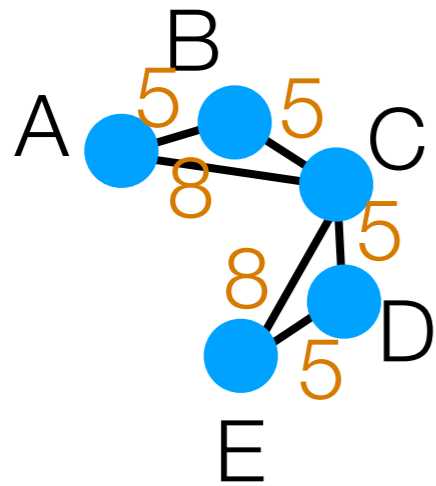
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	16
B		0	5	10	13
C			0	5	
D				0	5
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

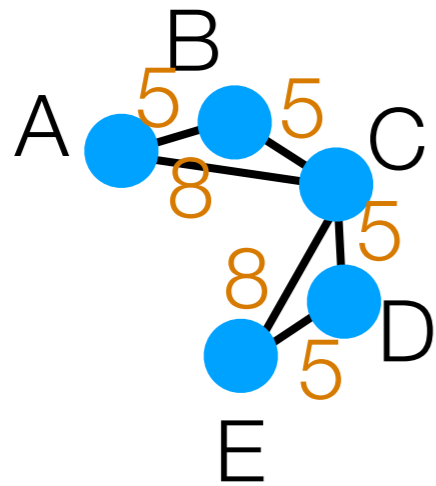
Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	16
B		0	5	10	13
C			0	5	8
D				0	5
E					0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

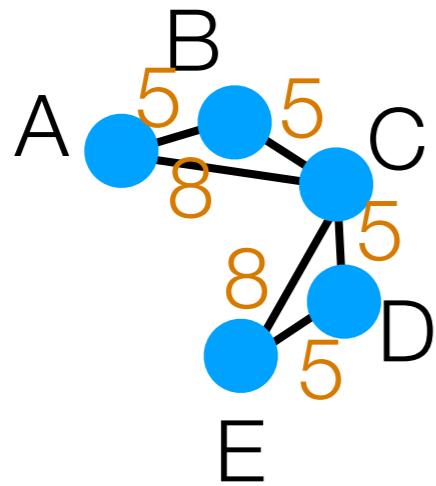
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Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	16
B	5	0	5	10	13
C	8	5	0	5	8
D	13	10	5	0	5
E	16	13	8	5	0

# Isomap Calculation Example

In orange: road lengths



2 nearest neighbors of A: B, C

2 nearest neighbors of B: A, C

2 nearest neighbors of C: B, D

2 nearest neighbors of D: C, E

2 nearest neighbors of E: C, D

Build "symmetric 2-NN" graph  
(add edges for each point to  
its 2 nearest neighbors)

Shortest distances between  
every point to every other  
point *where we are only  
allowed to travel along the  
roads*

	A	B	C	D	E
A	0	5	8	13	16
B	5	0	5	10	13
C	8	5	0	5	8
D	13	10	5	0	5
E	16	13	8	5	0

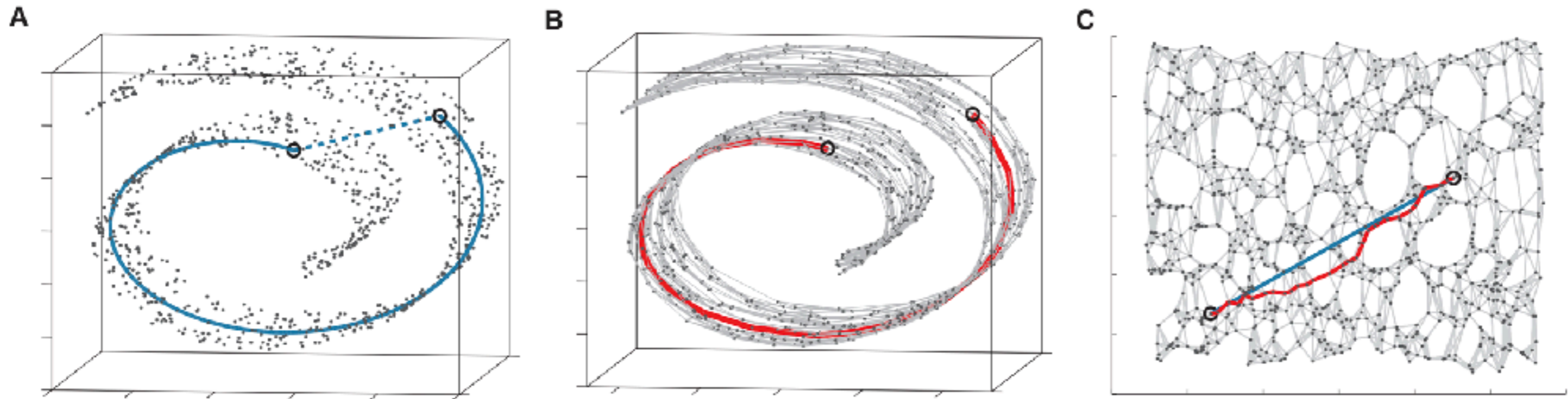
This matrix gets fed into  
*multidimensional scaling* to get  
1D version of A, B, C, D, E

The solution is not unique!

# Isomap Calculation Example

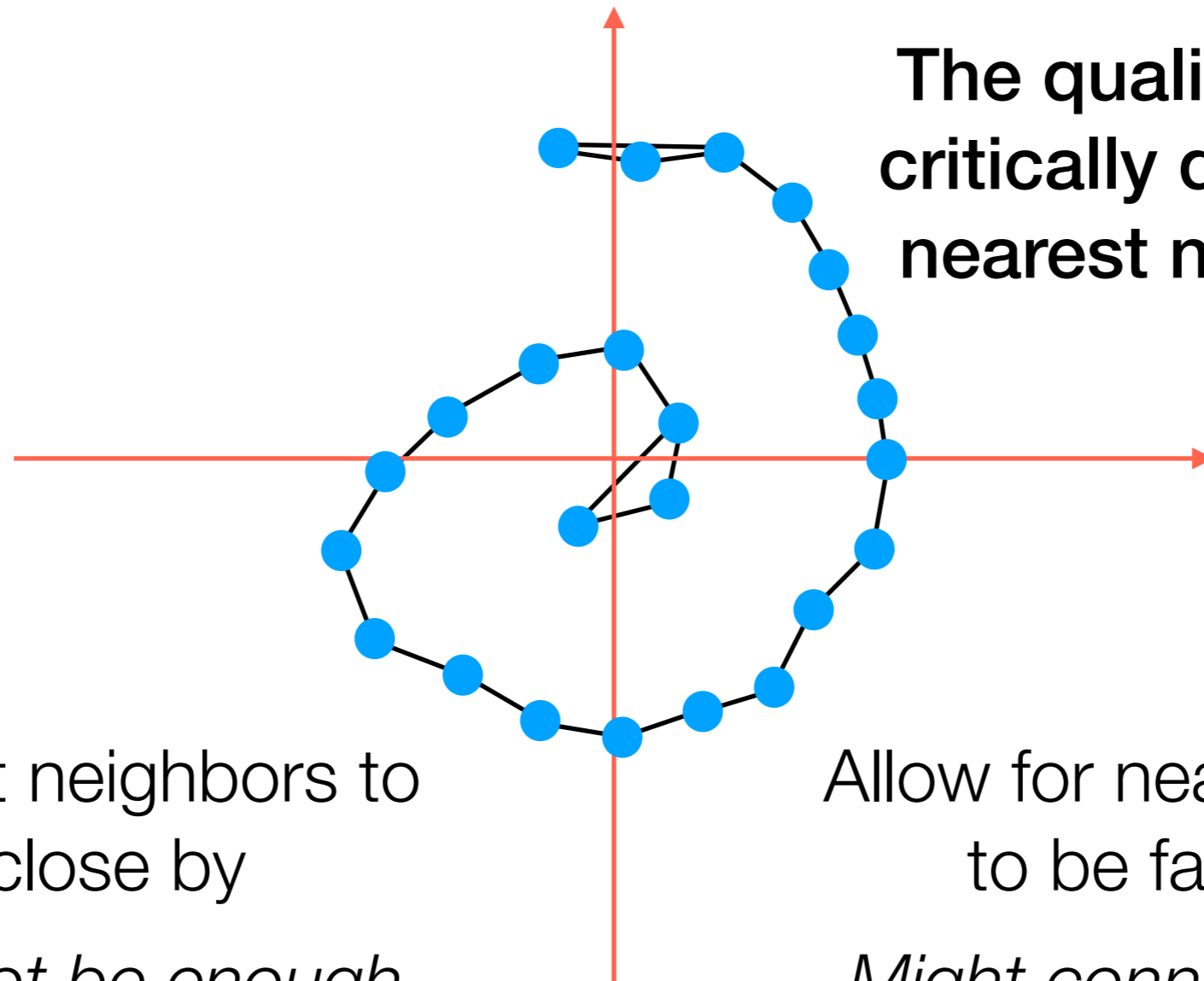
Multidimensional scaling demo

# 3D Swiss Roll Example



*Joshua B. Tenenbaum, Vin de Silva, John C. Langford. A Global Geometric Framework for Nonlinear Dimensionality Reduction. Science 2000.*

# Some Observations on Isomap



The quality of the result critically depends on the nearest neighbor graph

Ask for nearest neighbors to be really close by

*There might not be enough edges*

Allow for nearest neighbors to be farther away

*Might connect points that shouldn't be connected*

In general: try different parameters for nearest neighbor graph construction when using Isomap + visualize

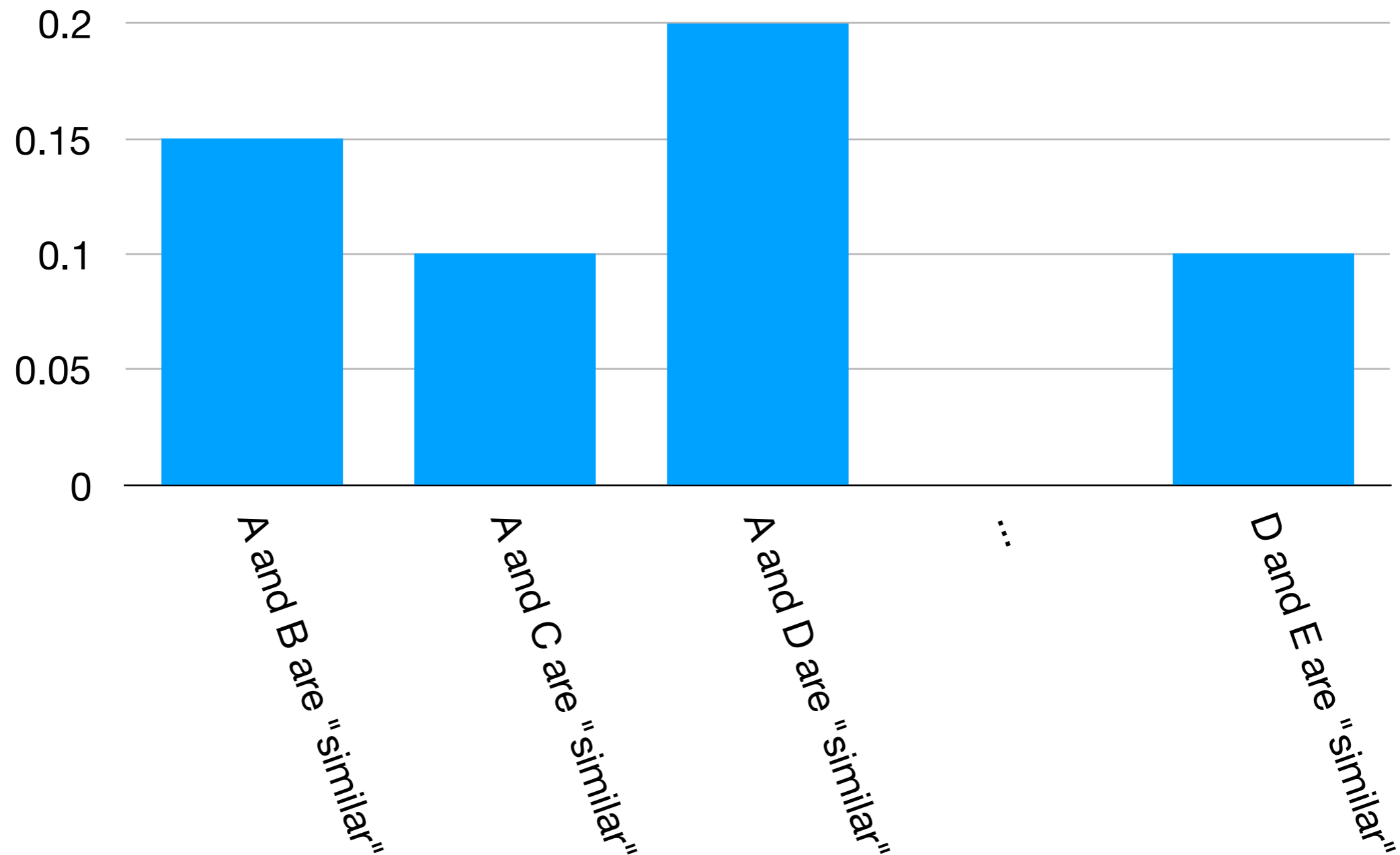


**t-SNE**

**(t-distributed stochastic  
neighbor embedding)**

# t-SNE High-Level Idea #1

- Don't use deterministic definition of which points are neighbors
- Use probabilistic notation instead

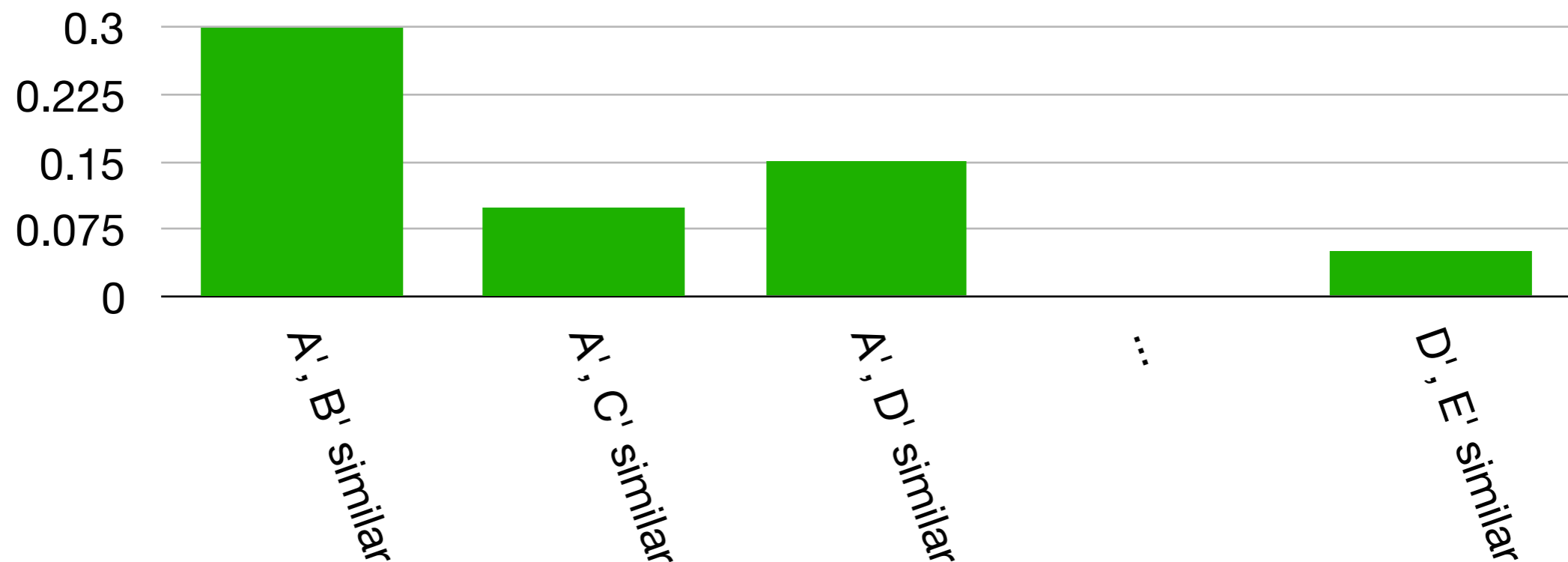


# t-SNE High-Level Idea #2

- In low-dim. space (e.g., 1D), suppose we just randomly assigned coordinates as a candidate for a low-dimensional representation for A, B, C, D, E (I'll denote them with primes):

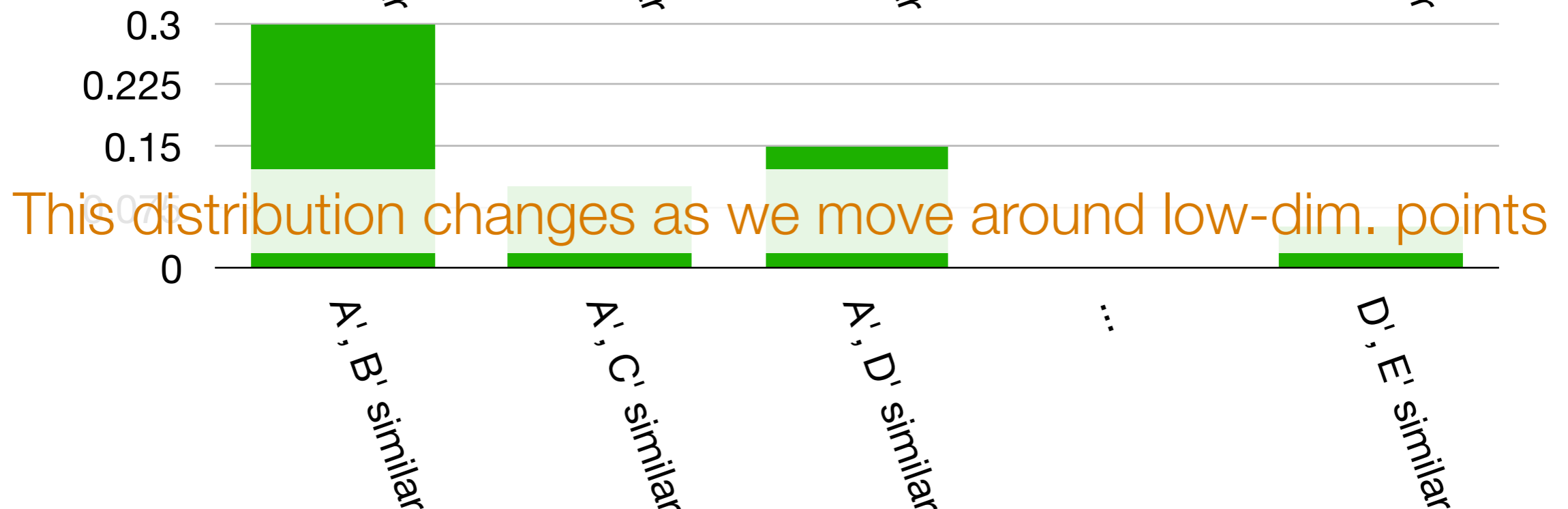
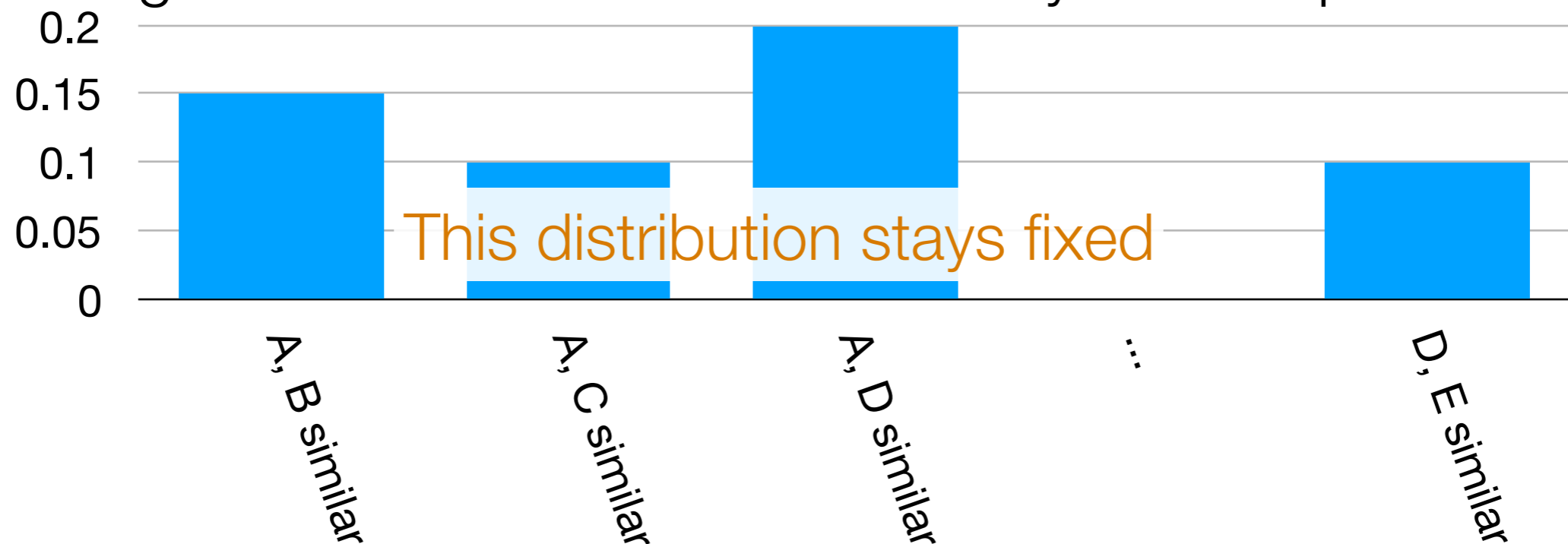


- With any such candidate choice, we can define a probability distribution for these low-dimensional points being similar



# t-SNE High-Level Idea #3

- Keep improving low-dimensional representation to make the following two distributions look as closely alike as possible



# Technical Detail for t-SNE

## Fleshing out high level idea #1

Suppose there are  $n$  high-dimensional points  $x_1, x_2, \dots, x_n$

For a specific point  $i$ , point  $i$  picks point  $j$  ( $\neq i$ ) to be a neighbor with probability:

$$p_{j|i} = \frac{\exp\left(-\frac{\|x_i - x_j\|^2}{2\sigma_i^2}\right)}{\sum_{k \neq i} \exp\left(-\frac{\|x_i - x_k\|^2}{2\sigma_i^2}\right)}$$

$\sigma_i$  (depends on  $i$ ) controls the probability in which point  $j$  would be picked by  $i$  as a neighbor (think about when it gets close to 0 or when it explodes to  $\infty$ )

$\sigma_i$  is controlled by a knob called 'perplexity'

(rough intuition: it is like selecting small vs large neighborhoods for Isomap)

Points  $i$  and  $j$  are "similar" with probability:  $p_{i,j} = \frac{p_{j|i} + p_{i|j}}{2n}$

This defines the earlier blue distribution

# Technical Detail for t-SNE

## Fleshing out high level idea #2

Denote the  $n$  low-dimensional points as  $x_1', x_2', \dots, x_n'$

Low-dim. points  $i$  and  $j$  are "similar" with probability:  $q_{i,j} = \frac{\frac{1}{1+\|x_i' - x_j'\|^2}}{\sum_{k \neq m} \frac{1}{1+\|x_k' - x_m'\|^2}}$

This defines the earlier green distribution

## Fleshing out high level idea #3

Approximately minimize (with respect to  $q_{i,j}$ ) the following cost:

$$\sum_{i \neq j} p_{i,j} \log \frac{p_{i,j}}{q_{i,j}}$$

This cost is called the "KL divergence" between distributions  $p$  and  $q$

# Manifold Learning with t-SNE

Demo

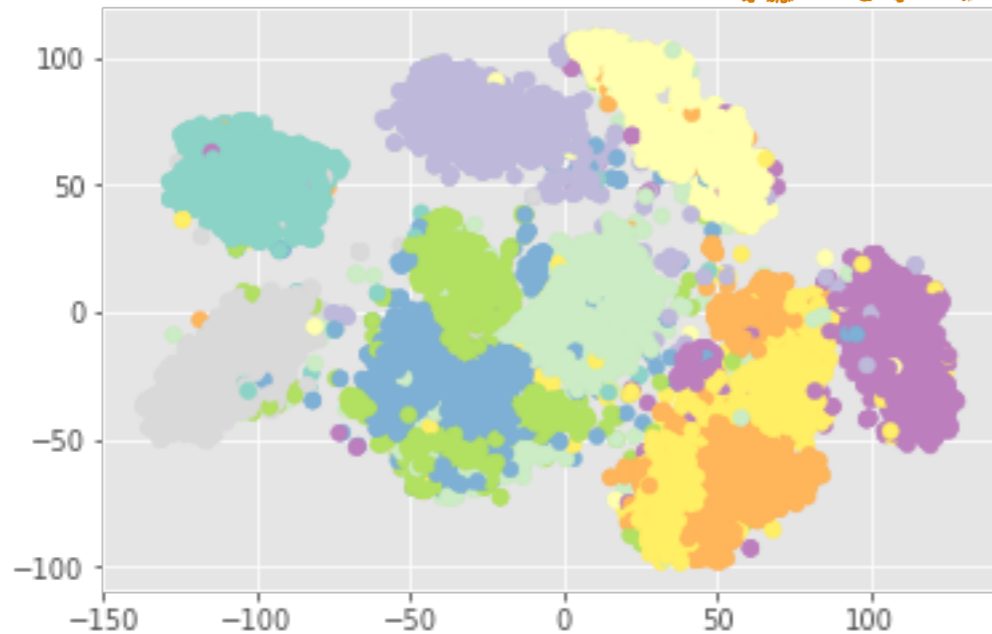
# t-SNE Interpretation

<https://distill.pub/2016/misread-tsne/>

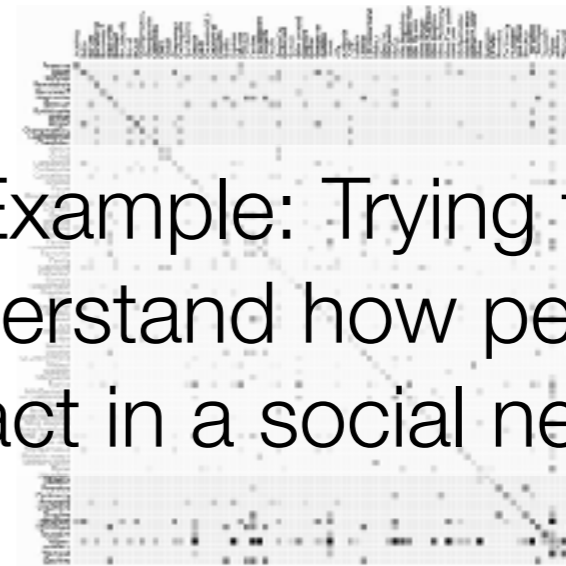


# Visualization

is a way of debugging data analysis!



Example: Trying to understand how people interact in a social network



## Important:

Handwritten digit demo was a **toy example** where we know which images correspond to digits 0, 1, ... 9

## Many real UDA problems:

The data are **messy** and it's not obvious what the "correct" labels/answers look like, and "correct" is ambiguous!

This is largely why I am covering "supervised" methods (require labels) *after* "unsupervised" methods (don't require labels)

# Dimensionality Reduction for Visualization

- There are *many* methods (I've posted a link on the course webpage to a scikit-learn example using ~10 methods)
- PCA is very well-understood; the new axes can be interpreted
- Nonlinear dimensionality reduction: new axes may not really be all that interpretable (you can scale axes, shift all points, etc)
- PCA and t-SNE are good candidates for methods to try first
- If you have good reason to believe that only certain features matter, of course you could restrict your analysis to those!